SEN6x – Datasheet

3rd Generation Environmental Sensor Node for Air Quality Applications

Highlights

- PM, RH&T, VOC, NO_x, CO_2/HCHO sensing platform
- Fast & easy integration
- 10 years dust resistant – Patented Sheath Flow technology
- Fully calibrated digital output
- One node for up to 9 data signals
- Integrated compensation algorithms
- Ready for California Title 24[1], RESET®[2] and WELL Building Standard™[3]

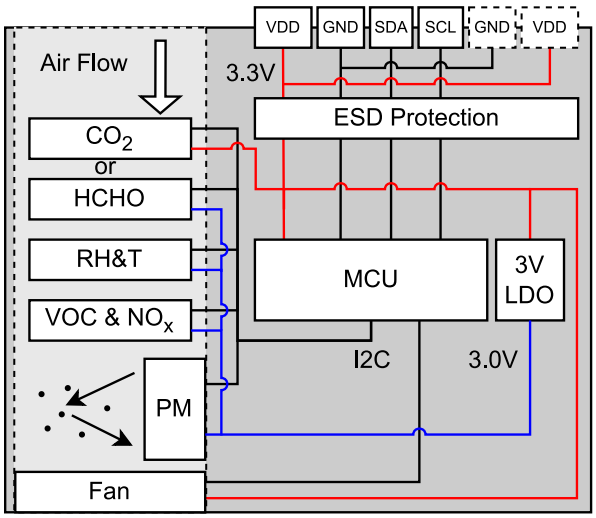
The SEN6x sensor module family is an air quality platform that combines critical parameters such as particulate matter, relative humidity, temperature, VOC, NO_x and either CO_2 or formaldehyde, all in one compact package. The modules are a result of Sensirion's extensive experience in environmental sensing and offer the best possible performance for each parameter, a superior lifetime and an unrivaled form factor. The combination of all measurement parameters, together with all relevant algorithms in one device simplifies the integration, streamlines the supply chain, and allows for a fast time to market with the best performance.

Product Overview

Product Variant	Sensor Signals
SEN62	PM, RH & T
SEN63C	PM, RH & T, CO_2
SEN65	PM, RH & T, VOC, NO_x
SEN66	PM, RH & T, VOC, NO_x, CO_2
SEN68	PM, RH & T, VOC, NO_x, HCHO
SEN69C	PM, RH & T, VOC, NO_x, HCHO, CO_2

See full product list on page 57

Functional Block Diagram



[1] 2022 California Building Energy Efficiency Standards for Residential and Nonresidential Buildings
[2] RESET Air Standard v2.0
[3] WELL v2

Contents

This is a preliminary datasheet; all specifications are to be understood as target specifications and can change without notice.

1 Environmental Sensor Node Specifications

For section **1.1** to **1.6**, default conditions of continuous measurement-mode, 25 °C, 50 %RH (relative humidity), 1013 mbar, and 3.3 V supply voltage apply, unless stated otherwise.
Different products within the SEN6x family offer different sensing capabilities. Specifications in the following only apply if the parameter is present in the selected product.

1.1 Sensor Module Specifications

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Default conditions as in section **1** apply to values in the table below, unless otherwise stated.

Parameter	Conditions	Value	Units
Sampling interval	-	1 ± 0.03	s
Sensor startup time (Time after power-on until I2C communication can be started)	-	100	ms
Lifetime[4,5]	24 h/day operation[6]	> 10	years
Acoustic emission level	0.2 m	< 24	dB(A)
Long term acoustic emission level drift	0.2 m	+0.5	dB(A) / year
Weight	-	20 ± 10 %	g

Table 1. Sensor Module Specifications

[4] Lifetime is based on mean-time-to-failure (MTTF) calculation. Lifetime might vary depending on different operating conditions. For more details refer to "SEN6x – Sensor Specification Statement" [10]
[5] Excluding formaldehyde specifications, formaldehyde lifetime limited to > 6 years
[6] For an indoor air quality mission profile

1.2 Particulate Matter Specifications

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Default conditions as in section **1** apply to values in the table below, unless otherwise stated.

Parameter	Conditions		Value	Units
Mass concentration specified range	-		0 to 1'000	µg/m³
Mass concentration size range	PM1.0		0.3 to 1.0	µm
	PM2.5		0.3 to 2.5	
	PM4		0.3 to 4.0	
	PM10		0.3 to 10.0	
Mass concentration precision[7,10] for PM1 and PM2.5[8]	0 to 100 µg/m³		±(5 µg/m³ + 5 % m.v.)	
	100 to 1000 µg/m³		±10	% m.v.
Mass concentration precision[7,10] for PM4, PM10[9]	0 to 100 µg/m³		±25	µg/m³
	100 to 1000 µg/m³		±25	% m.v.
Maximum long-term mass concentration precision limit drift[10]	0 to 100 µg/m³		±1.25	µg/m³ / year
	100 to 1000 µg/m³		±1.25	% m.v. / year
Typical start-up time[11]	-		30	s
Sensor output characteristics	PM2.5 mass concentration		Calibrated to TSI DustTrak™ DRX 8533 Ambient Mode	
Additional T-dependent mass precision limit drift[10]	temperature difference to 25°C	typ.	±0.5	% m.v. / °C
Laser wavelength (IEC 60825-1:2014 and DIN EN 60825-1:2022 Class 1) 	typ.		850	nm

Table 2. Particulate matter sensor specifications. '% m.v.' means '% of measured value'.

1.2.1 Laser Safety

This product is classified as a Class 1 laser product according to IEC 60825-1:2014 and DIN EN 60825-1:2022 standards. It is safe to operate without additional precautions. Do not open for servicing. Do not operate when damaged. Failure to follow this warning may result in direct exposure to the invisible Class 3R laser source and permanent eye damage.

[7] Also referred to as "between-parts variation" or "device-to-device variation".
[8] Verification Aerosol for PM2.5 is a 3% atomized KCl solution. Deviation to reference instrument is verified in end-tests for every sensor after calibration.
[9] PM4 and PM10 output values are calculated based on distribution profile of all measured particles.
[10] For more details refer to "SEN6x – Sensor Specification Statement" [10]
[11] Time after starting continuous measurement-mode, until a stable measurement is obtained.

1.3 Temperature and Humidity Specifications

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Default conditions as in section **1** apply to values in the table below, unless otherwise stated.

Parameter	Conditions	Value[12]			Units
		Min	Typ.	Max	
Compensated outputs[13]	-	Temperature			°C
		Relative Humidity			%RH
Accuracy temperature	@ 15-30 °C, 50 %RH	-	±0.45	±0.7	°C
Repeatability temperature	@ 25 °C, 50 %RH	-	0.1	-	
Response time temperature[14]	@ 25 °C, 50 %RH, $\tau_{63\%}$	-	<60	-	s
Accuracy relative humidity	@ 25 °C, 30-70 %RH	-	±4.5	±6	%RH
Repeatability relative humidity	@ 25 °C, 50 %RH	-	±1	-	
Response time relative humidity[15]	@ 25 °C, 50 %RH, $\tau_{63\%}$	-	<20	-	s

Table 3. Temperature and humidity specifications

[12] For the definition of the typical and max. accuracy tolerance, please refer to the document "Sensirion Humidity Sensor Specification Statement" [8].
[13] Self-heating of the module is compensated according to the application note "SEN6x – Temperature Acceleration and Compensation Instructions" [3].
[14] For a step from 15°C to 25°C, for a bare module with default acceleration and offset parameters
[15] For a step from 75%RH to 25%RH, for a bare module with default acceleration and offset parameters.

1.4 VOC and NO_x Specifications

Applies to: SEN65, SEN66, SEN68, SEN69C

Default conditions as in section **1** apply to values in the table below, unless otherwise stated.

Parameter	Description		Values			Units
			Min.	Typ.[16]	Max.	
Output signals	VOC Index		1	-	500	VOC Index points
	NOx Index		1	-	500	NOx Index points
	SRAW_VOC		0	-	65'535	ticks[17]
	SRAW_NO_x		0	-	65'535	
	TVOC output in ppb or µg/m^3 can be obtained by implementing application note: Compliance of Sensirion's VOC Sensors with Building Standards **[1]**.					ppb or µg/m^3
Device-to-device variation	VOC Index[18]		-	<±15 <±15	-	VOC Index points or % VOC Index m.v. (the larger)
	NOx Index[18]		-	<±50 <±50	-	NOx Index points or % NOx Index m.v. (the larger)
Repeatability	VOC Index[18]		-	<±5 <±5	-	VOC Index points or % VOC Index m.v. (the larger)
	NOx Index[18]		-	<±10 <±10	-	NOx Index points or % NOx Index m.v. (the larger)
Switch-on behavior	Time until reliably detecting events[19]	SRAW_VOC	-	<60	-	s
		SRAW_NOx	-	<300	-	
	Time until specifications in this table are met	VOC Index	-	<1	-	h
		NOx Index	-	<6	-	

Table 4. VOC and NO_x sensing specifications in zero air (considered as clean air for indoor air quality applications). All concentrations refer to ethanol as test gas.

[16] 95% of the sensors will be within the typical tolerance corresponding to 2σ assuming a normal distribution for ≥100 sensors.
[17] Ticks is proportional to the logarithm of the resistance of the sensing layer.
[18] Evaluated using the calibration and test sequence according to the application note "SGP40 – Quick Testing Guide" [9].
[19] Signal change during 60s event of 5'000 to 10'000 ppb of ethanol or of 100 to 300 ppb of NO_2 is three times larger than raw signals (SRAW_VOC, SRAW_NO_x) drift, without this event during the same duration.

1.5 CO_2 Specifications

Default conditions as in section **1** apply to values in the table below, unless otherwise stated. Continuous operation with automatic self-calibration (ASC) enabled and exposure to fresh air (i.e. CO_2 concentration at 400 ppm) at least once per week is required to achieve the following specifications.

1.5.1 CO_2 Specifications – SEN66

Applies to: SEN66

Accuracy is defined as deviation to a high-precision reference with gas mixtures having a ±2% tolerance and is achieved after either forced CO_2 recalibration (FRC) or initial operation for 2 days including exposure to fresh air.

Parameter	Conditions	Value	Units
CO_2 output range[20]	-	0 to 40'000	ppm
CO_2 measurement accuracy	400 ppm to 1'000 ppm	±(50 + 2.5 % m.v.)	
	1'001 ppm to 2'000 ppm	±(50 + 3 % m.v.)	
	2'001 ppm to 5'000 ppm	±(40 + 5 % m.v.)	
Additional accuracy drift per year, starting after five years[21]	400 to 5000 ppm, typ.	±(5 + 0.5 % m.v.)	
Repeatability	typ.	±10	
Response time	$\tau_{63\%}$, typical, step change 400 – 2'000 ppm	70	s

Table 5. CO_2 specifications, '% m.v.' means '% of measured value'.

1.5.2 CO_2 Specifications – SEN63C & SEN69C

Applies to: SEN63C, SEN69C

Accuracy is achieved after initial operation for 12 hours, followed by exposure to fresh air.

Parameters	Conditions	Value	Units
CO_2 output range[20]	-	380 to 32'000	ppm
CO_2 measurement accuracy	400 ppm to 5'000 ppm	±(100 + 10 % m.v.)	
Response time	$\tau_{63\%}$, typ., step change 2'000 – 400 ppm	60	s

Table 6. CO_2 specifications in ambient air (defined as consisting of 78% N_2, 21% O_2, 0.93% Ar, plus a variable content of CO_2 and H_2O depending on the relative humidity), '% m.v.' means '% of measured value'.

[20] Exposure to CO_2 concentrations smaller than 400 ppm can affect the accuracy of the sensor with ASC enabled.

[21] Deviation is additional to standard accuracy specifications. Maximum additional accuracy drift per year starting after five years estimated from stress tests is ± (5 ppm + 2% m.v.). Stronger drift may occur if the sensor is not handled according to its handling instructions.

1.6 Formaldehyde Specifications

Applies to: SEN68, SEN69C

Default conditions as in section **1** apply to values in the table below, unless otherwise stated.

Parameter	Conditions	Value	Units
Formaldehyde concentration measurement range	-	0 to 2000	ppb
Typical Accuracy	0 to 200 ppb HCHO in clean air	±20 ppb or ±20 % m.v. (the larger)	-
Maximum long-term accuracy drift	Standard conditions as defined in **section 1**	±5 ppb / year or ±5 % m.v. / year (the larger)	-
Cross-sensitivity to ethanol	Tested in 5 ppm ethanol	0.3 % (15 ppb)	-
Resolution	-	0.1	ppb
Typical start-up time	Time until sensor output is within specifications	10	min
Lifetime	Standard conditions as defined in **section 1**	≥6	years

Table 7. Formaldehyde specifications in ambient air (defined as consisting of 78% N_2, 21% O_2, 0.93% Ar, plus a variable content of CO_2, HCHO (Formaldehyde) and H_2O depending on the relative humidity), '% m.v.' means '% of measured value'.

1.7 Recommended and Absolute Maximum and Minimum Operating and Storage Conditions

The SEN6x family contains different sensing components with different operating and storage ranges. Make sure to select the appropriate table for the selected product.

1.7.1 SEN62

Table 8. and **Figure 1** show the recommended operating and storage conditions in which all the sensing components of the SEN62 show the best performance, as well as absolute maximum/minimum conditions which must not be exceeded.
Exposure to conditions outside the recommended range may temporarily reduce sensor performance (reversible RH drift, reduced RH, T, PM precision). Exposure to conditions outside the absolute maximum/minimum range may lead to permanent damage to the device.

The sensor must not be exposed to condensing conditions at any time.

Condition	Parameter	Recommended		Short-Term Maximum/Minimum[22]		Unit
		Min.	Max.	Min.	Max.	
Operating conditions	Temperature	10	40	-10	60	°C
	Relative humidity	20	80	0	95 (non-condensing)	% RH
Storage conditions	Temperature	10	40	-40	70	°C
	Relative Humidity	20	60	0	95 (non-condensing)	% RH

Table 8. Recommended and absolute maximum/minimum operating and storage conditions for the SEN62

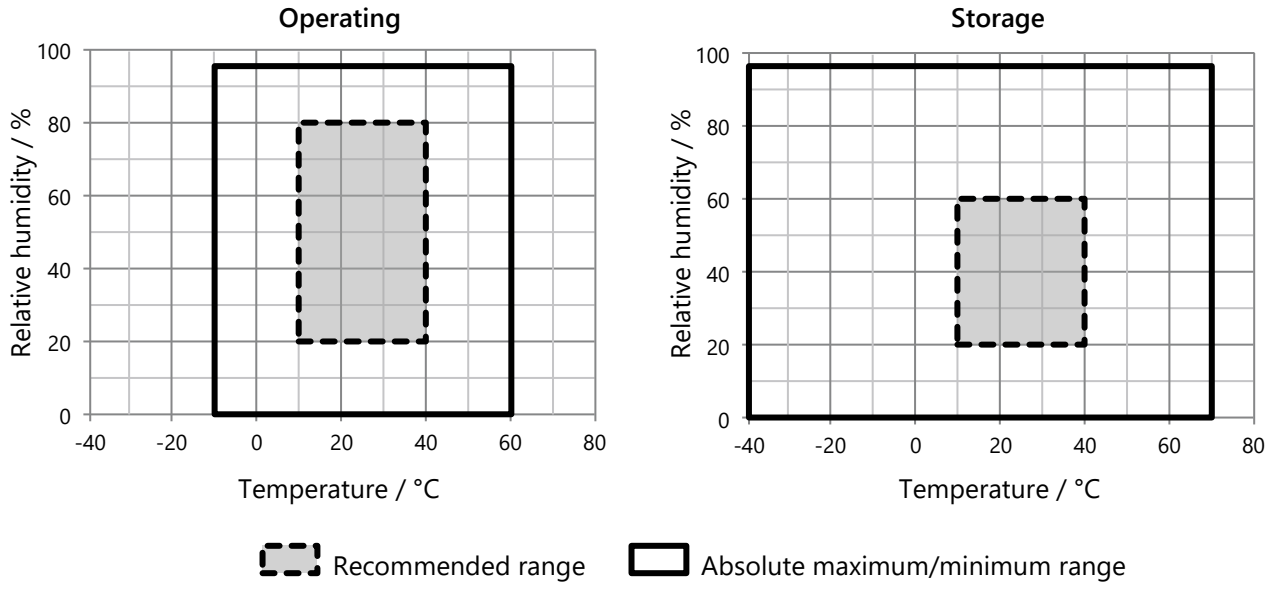


Figure 1. Recommended and absolute maximum/minimum operating and storage conditions for the SEN62

[22] Short-term storage refers to temporary conditions, e.g., transport.

1.7.2 SEN63C, SEN65 and SEN66

Table 9. and **Figure 2** show the recommended operating and storage conditions in which all the sensing components of the SEN63C, SEN65 and SEN66 show the best performance, as well as absolute maximum/minimum conditions which must not be exceeded. Gas sensing specifications are guaranteed only when the SEN63C, SEN65 and SEN66 are operated and stored under the recommended conditions given in **Table 9.** and **Figure 2**.
Exposure to conditions outside the recommended range may temporarily reduce sensor performance (reversible RH drift, reduced RH, T, VOC, NO_x, CO_2, PM precision). Exposure to conditions outside the absolute maximum/minimum range may lead to permanently reduced sensor performance (VOC and NO_x sensitivity drift) or cause permanent damage to the device.

The sensor must not be exposed to condensing conditions at any time.

Condition	Parameter	Recommended		Short Term- Maximum/Minimum[23]		Unit
		Min.	Max.	Min.	Max.	
Operating conditions	Temperature	10	40	-10	50	°C
	Relative humidity	20	80	0	90 (non-condensing)	% RH
Storage conditions	Temperature	10	30	-40	70	°C
	Relative Humidity	20	60	0	80 (non-condensing)	% RH

Table 9. Recommended and absolute maximum/minimum operating and storage conditions for the SEN63C, SEN65 and SEN66

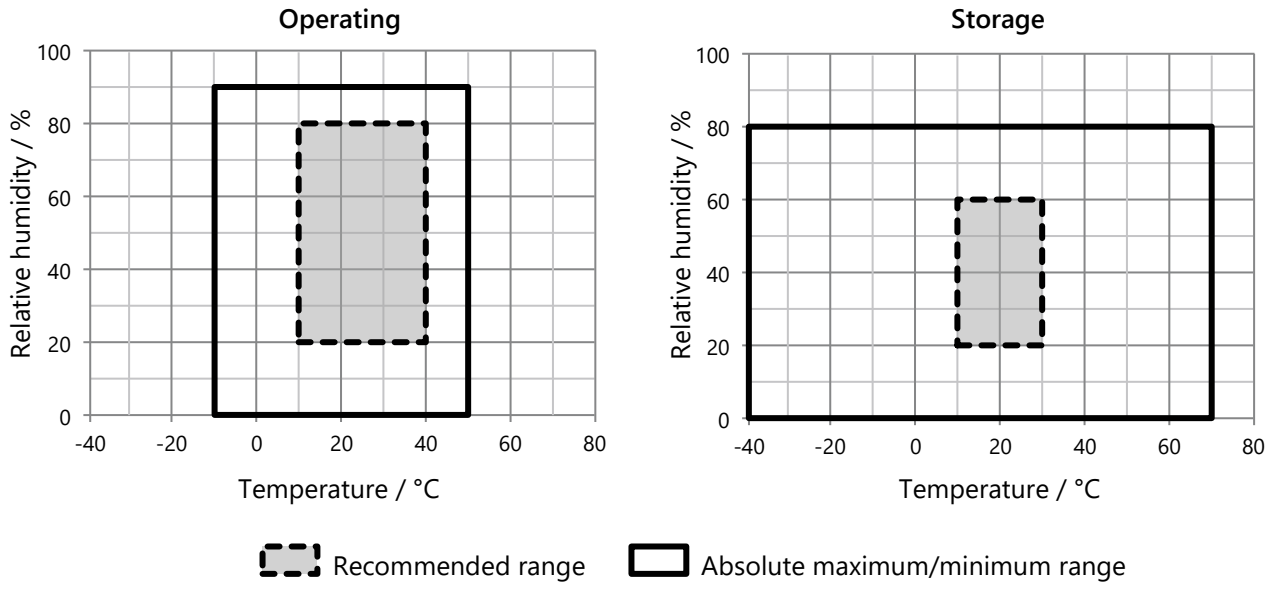


Figure 2. Recommended and absolute maximum/minimum operating and storage conditions for the SEN63C, SEN65 and SEN66

[23] Short-term storage refers to temporary conditions, e.g., transport.

1.7.3 SEN68 and SEN69C

Table 10. and **Figure 3** show the recommended operating and storage conditions in which all the sensing components of the SEN68 and SEN69C show the best performance, as well as absolute maximum/minimum conditions which must not be exceeded. Gas sensing specifications are guaranteed only when the SEN68 and SEN69C is operated and stored under the recommended conditions given in **Table 10.** and **Figure 3**.
Exposure to conditions outside the recommended range may temporarily reduce sensor performance (reversible RH drift, reduced RH, T, VOC, NO_x, CO_2, HCHO, PM precision). Exposure to conditions outside the absolute maximum/minimum range may lead to permanently reduced sensor performance (VOC, NO_x and HCHO sensitivity drift) or cause permanent damage to the device.

The sensor must not be exposed to condensing conditions at any time.

Condition	Parameter	Recommended		Short-Term Maximum/Minimum[24]		Unit
		Min.	Max.	Min.	Max.	
Operating conditions	Temperature	10	40	0	50	°C
	Relative humidity	20	80	15	90 (non-condensing)	% RH
Storage conditions	Temperature	10	30	-20	60	°C
	Relative Humidity	30	60	10	80 (non-condensing)	% RH

Table 10. Recommended and absolute maximum/minimum operating and storage conditions for the SEN68 and SEN69C

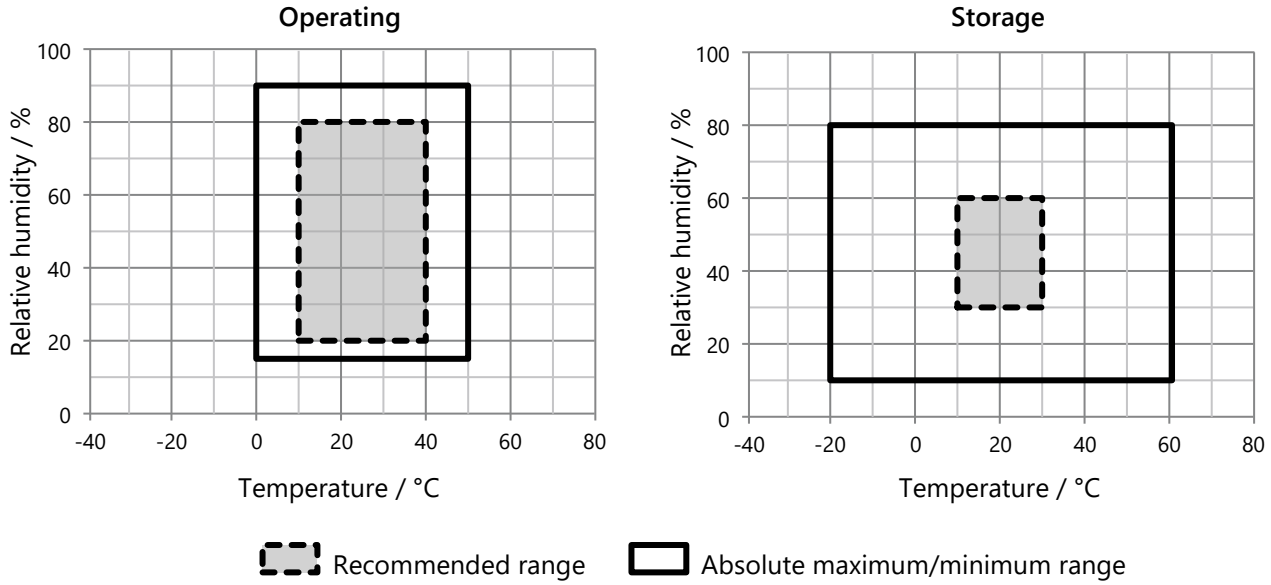


Figure 3. Recommended and absolute maximum/minimum operating and storage conditions for the SEN68 and SEN69C

[24] Short-term storage refers to temporary conditions, e.g., transport.

2 Electrical Specifications

2.1 Electrical Characteristics

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Parameter	Conditions		Min	Typ.	Max	Unit
Supply voltage (V_{DD})	-		3.15[25]	3.3	3.6	V
Supply voltage peak to peak ripple ($V_{DD,pp}$)	≥100 Hz	SEN6x	-	-	100	mV
	<100 Hz	SEN66	-	-	30	
		SEN6x	-	-	100	
Average supply current[26] (I_{DD})	Idle Mode (first 10 seconds)	SEN62	-	3.3	-	mA
		SEN63C	-	3.3	-	
		SEN65	-	4.6	-	
		SEN66	-	4.6	-	
		SEN68	-	4.6	-	
		SEN69C	-	4.6	-	
	Idle Mode (after first 10 seconds)	SEN62	-	3.3	-	
		SEN63C	-	3.3	-	
		SEN65	-	3.3	-	
		SEN66	-	3.3	-	
		SEN68	-	3.3	-	
		SEN69C	-	3.3	-	
	Measurement-Mode (after first 60 seconds)	SEN62	-	75	90	
		SEN63C	-	80	100	
		SEN65	-	80	100	
		SEN66	-	90	110	
		SEN68	-	75	100	
		SEN69C	-	75	100	
Peak supply current ($I_{DD,p}$)	Measurement mode (pulse width of 2 ms)	SEN62	-	130	190	
		SEN63C	-	140	200	
		SEN65	-	140	200	
		SEN66	-	300	350	
		SEN68	-	140	200	
		SEN69C	-	150	210	
SDA/SCL pin input high voltage (V_{IH})	-		0.7*V_{DD}	-	-	V
SDA/SCL pin input low voltage (V_{IL})			-	-	0.3*V_{DD}	
SDA pin output low voltage (V_{OL})	-		-	-	0.45	

Table 11. Electrical Specifications at 25°C

[25] Minimum voltage including ripples.
[26] Averaged over 5 seconds

2.2 Absolute Maximum Ratings

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Stress levels beyond those listed in **Table 12** may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these conditions cannot be guaranteed. Exposure to the absolute maximum rating conditions for extended periods may affect the reliability of the device.

Parameter	Min	Max	Unit
Supply voltage VDD	0	3.6	V
I/O pins (SDA, SCL)	-0.3	5.5	
Max. current on any I/O pin	-20	20	mA

Table 12. Absolute minimum and maximum ratings

2.3 ESD / EMC Ratings

2.3.1 Immunity

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description	Standard	Rating
Electrostatic Discharge	IEC 61000-4-2	±4 kV contact, ±4 kV air
Power-Frequency Magnetic Field	IEC 61000-4-8	30 A/m, 50 Hz and 60 Hz
Radio-Frequency EM-Field AM-modulated	IEC 61000-4-3	80 MHz – 1000 MHz, 3 V/m, 80% AM @1 kHz
Radio-Frequency EM-Field AM-modulated	IEC 61000-4-3	1.4 GHz – 6 GHz, 3 V/m, 80% AM @1 kHz

Table 13. ESD and EMC immunity

2.3.2 Emission

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description	Standard	Rating
Emission in SAC for 30MHz to 230MHz	IEC/CISPR 16	40 dB(µV/m) QP @3m
Emission in SAC for 230MHz to 1000MHz	IEC/CISPR 16	47 dB(µV/m) QP @3m

Table 14. EMC emission

3 Hardware Interface Description

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

The sensor is equipped with a serial communication interface. In **Table 16**, a description of the pin layout is given.

Part	Description
Connector sensor side	ACES 51468-0064N-001
Connector cable side	ACES 51452-006H0H0-001 or compatible (e.g., JST GHR-06V-S)
Cable cross section area	≥AWG26 (≥0.128 mm^2)
Cable length	≤50 cm

Table 15. SEN6x physical interface

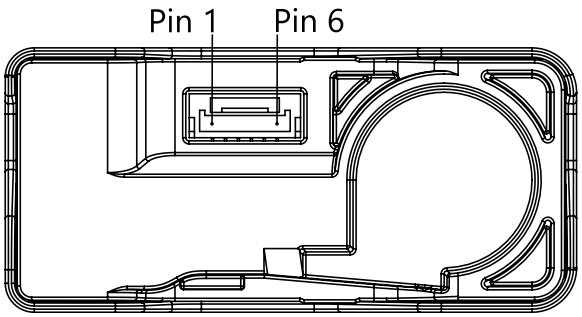


Figure 4. Pin layout. The communication interface connector (ACES 51468-0064N-001) is located at the side of the sensor adjacent to the air outlet.

Pin	Name	Description	Comments
1	VDD	Supply voltage	-
2	GND	Ground	-
3	SDA	Serial data input/output	TTL 5V compatible
4	SCL	Serial clock input	TTL 5V compatible
5	GND	Ground or NC	Pins 2 and 5 are connected internally
6	VDD	Supply voltage or NC	Pins 1 and 6 are connected internally

Table 16. SEN6x pin assignment

3.1 I^{2}C Interface Circuit

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

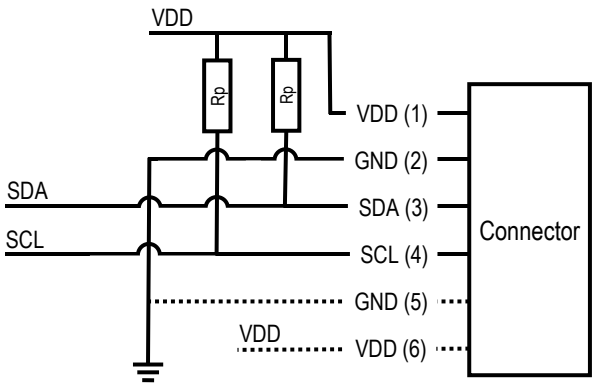


Figure 5. I^{2}C application circuit

Both SCL and SDA lines are open drain I/Os. They must be connected to external pull-up resistors (e.g. Rp = 10 kΩ).

SEN6x uses an I^{2}C interface, which was originally designed to connect two chips on a PCB at relatively close distance. Hence, when the sensor is connected to the main PCB via a cable, particular attention must be paid to electromagnetic interference and crosstalk. Use as short as possible (< 10 cm) and/or well shielded connection cables.

For detailed information on the I^{2}C protocol, refer to NXP I^{2}C-bus specification [2].

4 Digital Interface Description

4.1 Operation Modes

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

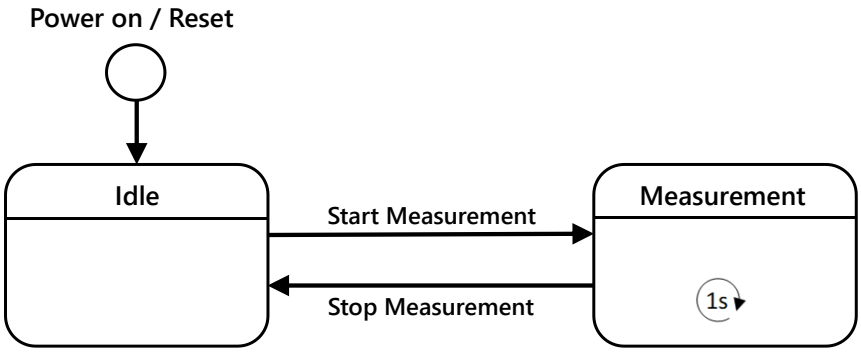


Figure 6. SEN6x operating modes

Idle:

- The module is in Idle Mode after power on or reset.
- Most of the internal electronics switched off / reduced power consumption.
- Fan and laser are switched off.
- The module is ready to receive and process any command.

Measurement:

- All electronics switched on / max. power consumption.
- The measurement is running, and the module is continuously processing measurement data.
- New readings are available every second.

4.2 Temperature Compensation with STAR Engine

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

By default, the temperature and humidity outputs from the sensor are compensated for the module's self-heating. If the module is designed into a device, the temperature compensation might need to be adapted to incorporate the change in thermal coupling and self-heating of other device components. A guide to achieve optimal performance, including references to mechanical design-in examples can be found in the app note "SEN6x – Temperature Acceleration and Compensation Instructions" [3].

4.3 Device Status Register

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

The device status register contains information about the internal state of the module.

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
										Warning					
res.	res.	res.	res.	res.	res.	res.	res.	res.	res.	SPEED	res.	res.	res.	res.	res.
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
			Error	Error	Error	Error		Error	Error		Error				
res.	res.	res.	CO_2-1	PM	HCHO	CO_2-2	res.	GAS	RH&T	res.	FAN	res.	res.	res.	res.

Figure 7. Device status register description

4.3.1 SPEED – Fan Speed Warning

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Fan Speed Warning		
Bit	21 (see **Figure 7**)	
State	0	Fan speed is ok
	1	Fan speed is too high or too low
Sticky	No	
Description	Fan is switched on, but its speed is more than 10% off the target speed for multiple consecutive measurement intervals. During the first 10 seconds after starting the measurement, the fan speed is not checked (settling time). Very low or very high ambient temperature could trigger this warning during startup. If this flag is set constantly, it might indicate a problem with the power supply or with the fan, and the measured PM values might be wrong. This flag is automatically cleared as soon as the measured speed is within 10% of the target speed or when leaving the measurement mode. Can occur only in measurement mode.	

Table 17. Fan speed warning bit description

4.3.2 CO_2-1 – CO_2 Sensor Error

Applies to: SEN63C, SEN69C

CO2-1 Sensor Error		
Bit	12 (see **Figure 7**)	
State	0	CO_2 sensor is running normally
	1	CO_2 sensor error
Sticky	Yes – Even if the error disappears or when leaving the measurement mode, the flag remains set. This flag will only be reset by **Read And Clear Device Status** or through a reset, either by calling **Device Reset** or through a power cycle.	
Description	Error related to the CO_2 sensor. The CO_2 values might be unknown or wrong if this flag is set, relative humidity and temperature values might be out of specs due to compensation algorithms depending on CO_2 sensor state. Can occur only in measurement mode.	

Table 18. CO_2-1 sensor error bit description

4.3.3 PM – Particulate Matter Sensor Error

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

PM Sensor Error		
Bit	11 (see **Figure 7**)	
State	0	PM sensor is running normally
	1	PM sensor error
Sticky	Yes – Even if the error disappears or when leaving the measurement mode, the flag remains set. This flag will only be reset by **Read And Clear Device Status** or through a reset, either by calling **Device Reset** or through a power cycle.	
Description	Error related to the PM sensor. The particulate matter values might be unknown or wrong if this flag is set, relative humidity and temperature values might be out of specs due to compensation algorithms depending on PM sensor state. Can occur only in measurement mode.	

Table 19. PM sensor error bit description

4.3.4 HCHO – Formaldehyde Sensor Error

Applies to: SEN68, SEN69C

Formaldehyde Sensor Error		
Bit	10 (see **Figure 7**)	
State	0	Formaldehyde sensor is running normally
	1	Formaldehyde sensor error
Sticky	Yes – Even if the error disappears or when leaving the measurement mode, the flag remains set. This flag will only be reset by **Read And Clear Device Status** or through a reset, either by calling **Device Reset** or through a power cycle.	
Description	Error related to the formaldehyde sensor. The formaldehyde values might be unknown or wrong if this flag is set, relative humidity and temperature values might be out of specs due to compensation algorithms depending on formaldehyde sensor state. Can occur only in measurement mode.	

Table 20. Formaldehyde sensor error bit description

4.3.5 CO_2-2 – CO_2 Sensor Error

Applies to: SEN66

CO2-2 Sensor Error		
Bit	9 (see **Figure 7**)	
State	0	CO_2 sensor is running normally
	1	CO_2 sensor error
Sticky	Yes – Even if the error disappears or when leaving the measurement mode, the flag remains set. This flag will only be reset by **Read And Clear Device Status** or through a reset, either by calling **Device Reset** or through a power cycle.	
Description	Error related to the CO_2 sensor. The CO_2 values might be unknown or wrong if this flag is set, relative humidity and temperature values might be out of specs due to compensation algorithms depending on CO_2 sensor state. Can occur only in measurement mode.	

Table 21. CO2-2 sensor error bit description

4.3.6 GAS – Gas Sensor Error (VOC and NO_x)

Applies to: SEN65, SEN66, SEN68, SEN69C

Gas Sensor Error		
Bit	7 (see **Figure 7**)	
State	0	Gas sensor is running normally
	1	Gas sensor error
Sticky	Yes – Even if the error disappears or when leaving the measurement mode, the flag remains set. This flag will only be reset by **Read And Clear Device Status** or through a reset, either by calling **Device Reset** or through a power cycle.	
Description	Error related to the gas sensor. The VOC index and NOx index might be unknown or wrong if this flag is set, relative humidity and temperature values might be out of specs due to compensation algorithms depending on gas sensor state. Can occur only in measurement mode.	

Table 22. Gas sensor error bit description

4.3.7 RH&T – Relative Humidity and Temperature Sensor Error

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

RH&T Sensor Error		
Bit	6 (see **Figure 7**)	
State	0	RH&T sensor is running normally
	1	RH&T sensor error
Sticky	Yes – Even if the error disappears or when leaving the measurement mode, the flag remains set. This flag will only be reset by **Read And Clear Device Status** or through a reset, either by calling **Device Reset** or through a power cycle.	
Description	Error related to the RH&T sensor. The temperature and humidity values might be unknown or wrong if this flag is set, and other measured values might be out of specs due compensation algorithms depending on RH&T sensor values. Can occur only in measurement mode.	

Table 23. RH&T sensor error bit description

4.3.8 FAN – Fan Error

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Fan Error		
Bit	4 (see **Figure 7**)	
State	0	Fan running normally
	1	Fan error
Sticky	Yes – if the error disappears or when leaving the measurement mode, the flag remains set. This flag will only be reset by **Read And Clear Device Status** or through a reset, either by calling **Device Reset** or through a power cycle.	
Description	Fan is switched on, but 0 RPM is measured for multiple consecutive measurement intervals. This can occur if the fan is mechanically blocked or broken. Note that the measured values are most likely wrong if this error is reported. Can occur only in measurement mode.	

Table 24. Fan error bit description

4.4 I²C Interface Settings

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Property	Description
I²C Address	0x6B (7-bit)
Max. Speed	100kbit/s (standard mode)
Clock stretching	Not used, the sensor NACKs when busy with processing

Table 25. I²C interface settings

4.5 Power-Up and Communication Start

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

The sensor starts powering-up after reaching the power-up threshold voltage $V_{DD,min}$ and will take up to the maximum of the sensor startup time, specified in **Table 1**, to enter the idle state. Once the idle state has been reached, it is ready to receive commands from the controller. Any incoming command will be acknowledged (address header and all data bytes). After the stop condition, the sensor validates and processes the received data. During this time, the sensor does not acknowledge any I²C requests (address header will be NACK'd). As soon as the command is fully processed, the I²C interface becomes ready again. The controller can then either read the result with a read operation or send the next command with a write operation.

4.6 Data Type & Length

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Data sent to and received from the sensor consists of a sequence of 16-bit words, most significant byte (MSB) transmitted first. Each word is succeeded by an 8-bit CRC. See **Figure 8** for more detail. In write direction it is mandatory to transmit the checksum. In read direction it is up to the controller to decide whether to process the checksum.

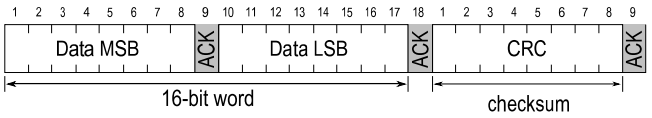


Figure 8. Data type structure with 16-bit word and 8-bit CRC

Please note that the CRC is used only for the 16-bit data packets. The 16-bit command ID itself already contains a 3-bit CRC and therefore no CRC must be appended to it as seen in **Figure 9**. Each command ID is represented by a 4-digit Hex. Code as seen in **Table 26.**

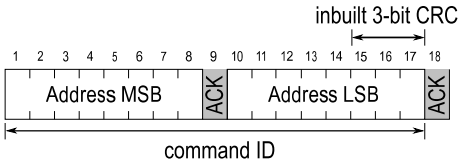


Figure 9. Command ID with inbuilt 3-bit CRC

4.7 Command Sequence Types

The SEN6x features four different I²C command sequence types: write I²C sequences, send I²C command sequence, read I²C sequences and send & fetch I²C sequence. **Figure 10** illustrates how the I²C communication for the different sequence types is built up. For detailed information on the I²C protocol, refer to NXP I²C-bus specification [2].

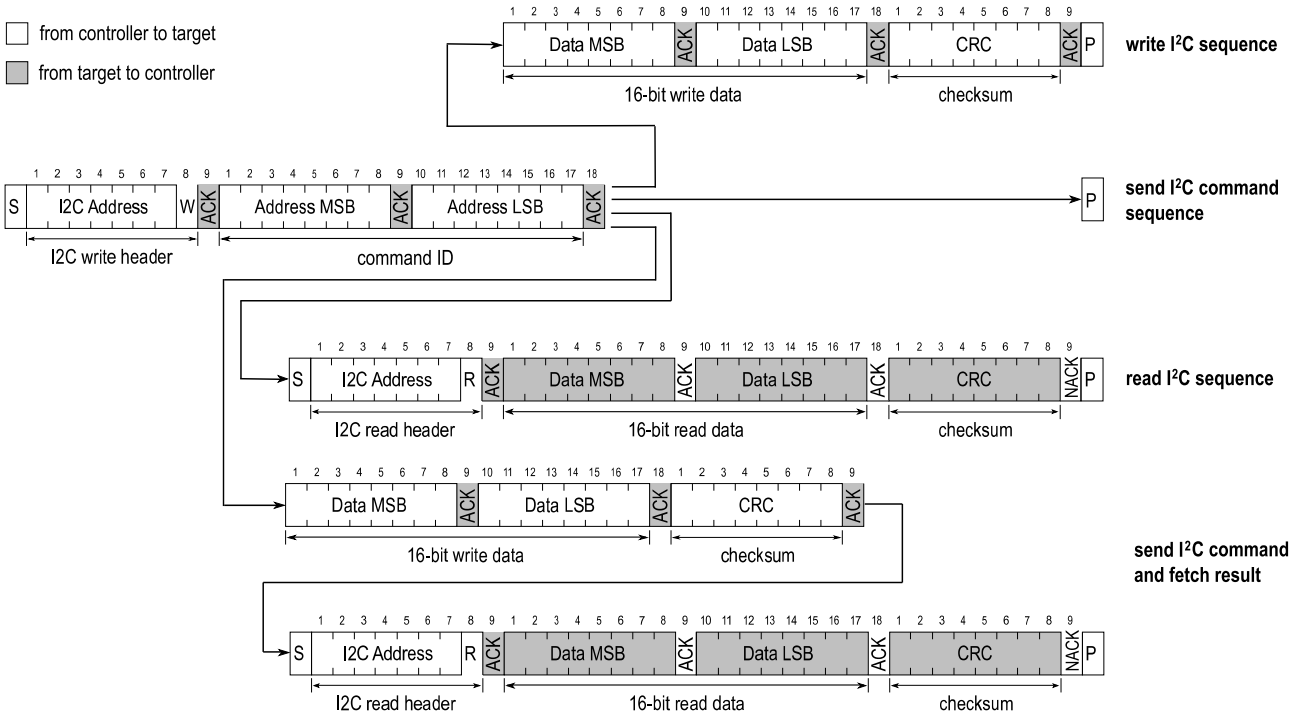


Figure 10. Command sequence types: write sequence, send command sequence, read sequence and send command and fetch result sequence

After issuing read sequence commands and sending the ACK Bit, the sensor needs the *execution time* (see **Table 26**) to respond to the I²C read header with an ACK bit. Hence, it is required to wait the command execution time before issuing the read header. Commands must not be sent while a previous command is being processed.

4.8 I²C Commands

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Command ID	Command	I²C Sequence Type (see Section 4.7)	Execution		Applicable to					
			Time [ms]	During Measur.	SEN62	SEN63C	SEN65	SEN66	SEN68	SEN69C
0x0021	Start Continuous Measurement	send	50	no	✓	✓	✓	✓	✓	✓
0x0104	Stop Measurement	send	1400	yes	✓	✓	✓	✓	✓	✓
0x0202	Get Data Ready	read	20	yes	✓	✓	✓	✓	✓	✓
0x04A3	Read Measured Values SEN62	read	20	yes	✓	-	-	-	-	-
0x0471	Read Measured Values SEN63C	read	20	yes	-	✓	-	-	-	-
0x0446	Read Measured Values SEN65	read	20	yes	-	-	✓	-	-	-
0x0300	Read Measured Values SEN66	read	20	yes	-	-	-	✓	-	-
0x0467	Read Measured Values SEN68	read	20	yes	-	-	-	-	✓	-
0x0467	Read Measured Values SEN68	read	20	yes	-	-	-	-	✓	-
0x04B5	Read Measured Values SEN69C	read	20	yes	-	-	-	-	-	✓
0x0492	Read Measured Raw Values SEN62, SEN63C	read	20	yes	✓	✓	-	-	-	-
0x0455	Read Measured Raw Values SEN65, SEN68, SEN69C	read	20	yes	-	-	✓	-	✓	✓
0x0405	Read Measured Raw Values SEN66	read	20	yes	-	-	-	✓	-	-
0x0316	Read Number Concentration Values	read	20	yes	✓	✓	✓	✓	✓	✓
0x60B2	Set Temperature Offset Parameters	write	20	yes	✓	✓	✓	✓	✓	✓
0x6100	Set Temperature Acceleration Parameters	write	20	no	✓	✓	✓	✓	✓	✓
0xD014	Get Product Name	read	20	yes	✓	✓	✓	✓	✓	✓
0xD033	Get Serial Number	read	20	yes	✓	✓	✓	✓	✓	✓
0xD206	Read Device Status	read	20	yes	✓	✓	✓	✓	✓	✓
0xD210	Read And Clear Device Status	read	20	yes	✓	✓	✓	✓	✓	✓
0xD100	Get Version	read	20	yes	✓	✓	✓	✓	✓	✓
0xD304	Device Reset	send	1200	no	✓	✓	✓	✓	✓	✓
0x5607	Start Fan Cleaning	send	20	no	✓	✓	✓	✓	✓	✓
0x6765	Activate SHT Heater	send	20	no	✓	✓	✓	✓	✓	✓
0x6790	Get SHT Heater Measurements	read	20	no	✓	✓	✓	✓	✓	✓
0x60D0	Get VOC Algorithm Tuning Parameters	read	20	no	-	-	✓	✓	✓	✓
0x60D0	Set VOC Algorithm Tuning Parameters	write	20	no	-	-	✓	✓	✓	✓
0x6181	Get VOC Algorithm State	read	20	yes	-	-	✓	✓	✓	✓
0x6181	Set VOC Algorithm State	write	20	no	-	-	✓	✓	✓	✓
0x60E1	Get NOx Algorithm Tuning Parameters	read	20	no	-	-	✓	✓	✓	✓
0x60E1	Set NOx Algorithm Tuning Parameters	write	20	no	-	-	✓	✓	✓	✓
0x6707	Perform Forced CO2 Recalibration	send and fetch	500	no	-	✓	-	✓	-	✓
0x6754	Perform CO_2 Sensor Factory Reset	send	1400	no	-		-	✓	-	✓
0x6711	Get CO2 Sensor Automatic Self Calibration	read	20	no	-	✓	-	✓	-	✓
0x6711	Set CO2 Sensor Automatic Self Calibration	write	20	no	-	✓	-	✓	-	✓
0x6720	Get Ambient Pressure	read	20	yes	-	✓	-	✓	-	✓
0x6720	Set Ambient Pressure	write	20	yes	-	✓	-	✓	-	✓
0x6736	Get Sensor Altitude	read	20	no	-	✓	-	✓	-	✓
0x6736	Set Sensor Altitude	write	20	no	-	✓	-	✓	-	✓

Table 26. Command overview. The column ('During measurement') indicates whether the command can be executed in the measurement mode.

4.8.1 Start Continuous Measurement

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: Starts a continuous measurement. After starting the measurement, it takes some time (~1.1s) until the first measurement results are available. You could poll with the command **Get Data Ready** to check when the results are ready to be read.

Note: For SEN63C and SEN69C only: SEN63C and SEN69C are conditioning the CO_2 sensor during the initial 24 seconds after starting a measurement. As this process cannot be interrupted, the following limitations apply during this period:

- You may stop the measurement if needed, but do not start it again until at least 24 seconds have passed to avoid a **CO2-1 – CO2 Sensor Error**.
- Do not stop the sensor and use the commands **Perform Forced CO2 Recalibration**, **Set CO2 Sensor Automatic Self Calibration** or **Perform CO2 Sensor Factory Reset**.

Start Continuous Measurement	
Command ID	0x0021
Available in	Idle mode
Execution Time	50 ms
Max. RX Data With CRC	0 Bytes
TX Data	None
RX Data	None

Table 27. Start continuous measurement I^2C command description

4.8.2 Stop Measurement

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: Stops the measurement and returns to idle mode. After sending this command, wait at least 1400 ms before starting a new measurement.

Stop Measurement	
Command ID	0x0104
Available in	Measurement mode
Execution Time	1400 ms
Max. RX Data With CRC	0 Bytes
TX Data	None
RX Data	None

Table 28. Stop measurement I^2C command description

4.8.3 Get Data Ready

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: This command can be used to check if new measurement results are ready to read. The data ready flag is automatically reset after reading the measurement values.

Get Data Ready			
Command ID	0x0202		
Available in	Measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	3 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0		Padding: `uint8` Padding byte, always 0x00.
	1		Data Ready: `bool8` True (0x01) if data is ready, False (0x00) if not. When no measurement is running, False will be returned.
	2	CRC	CRC for the previous two bytes.

Table 29. Get data ready I^2C command description

4.8.4 Read Measured Values SEN62

Applies to: SEN62

Description: Returns the measured values. The command **Get Data Ready** can be used to check if new data is available since the last read operation. If no new data is available, the previous values will be returned. If no data is available at all (e.g. measurement not running for at least one second), all values will be at their upper limit (0xFFFF for `uint16`, 0x7FFF for `int16`).

Read Measured Values SEN62			
Command ID	0x04A3		
Available in	Measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	18 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Mass Concentration PM1.0: `uint16`
	1	LSB	Value is scaled with factor 10: PM1.0 [μg/m^3] = value / 10
	2	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	3	MSB	Mass Concentration PM2.5: `uint16`
	4	LSB	Value is scaled with factor 10: PM2.5 [μg/m^3] = value / 10
	5	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	6	MSB	Mass Concentration PM4.0: `uint16`
	7	LSB	Value is scaled with factor 10: PM4.0 [μg/m^3] = value / 10
	8	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	9	MSB	Mass Concentration PM10.0: `uint16`
	10	LSB	Value is scaled with factor 10: PM10.0 [μg/m^3] = value / 10
	11	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	12	MSB	Ambient Humidity: `int16`
	13	LSB	Value is scaled with factor 100: RH [%] = value / 100
	14	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	15	MSB	Ambient Temperature: `int16`
	16	LSB	Value is scaled with factor 200: T [°C] = value / 200
	17	CRC	*Note: If this value is unknown, 0x7FFF is returned.*

Table 30. Read measured values SEN62 I^{2}C command description

4.8.5 Read Measured Values SEN63C

Applies to: SEN63C

Description: Returns the measured values. The command **Get Data Ready** can be used to check if new data is available since the last read operation. If no new data is available, the previous values will be returned. If no data is available at all (e.g. measurement not running for at least one second), all values will be at their upper limit (0xFFFF for `uint16`, 0x7FFF for `int16`).

Read Measured Values SEN63C			
Command ID	0x0471		
Available in	Measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	21 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Mass Concentration PM1.0: `uint16`
	1	LSB	Value is scaled with factor 10: PM1.0 [$\mu g/m^3$] = value / 10
	2	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	3	MSB	Mass Concentration PM2.5: `uint16`
	4	LSB	Value is scaled with factor 10: PM2.5 [$\mu g/m^3$] = value / 10
	5	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	6	MSB	Mass Concentration PM4.0: `uint16`
	7	LSB	Value is scaled with factor 10: PM4.0 [$\mu g/m^3$] = value / 10
	8	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	9	MSB	Mass Concentration PM10.0: `uint16`
	10	LSB	Value is scaled with factor 10: PM10.0 [$\mu g/m^3$] = value / 10
	11	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	12	MSB	Ambient Humidity: `int16`
	13	LSB	Value is scaled with factor 100: RH [%] = value / 100
	14	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	15	MSB	Ambient Temperature: `int16`
	16	LSB	Value is scaled with factor 200: T [°C] = value / 200
	17	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	18	MSB	CO2: `int16`
	19	LSB	CO2 concentration [ppm]
	20	CRC	*Note: If this value is unknown, 0x7FFF is returned. During the first 22..24 seconds starting a measurement, this value will be 0x7FFF.*

Table 31. Read measured values SEN63C I^2C command description

4.8.6 Read Measured Values SEN65

Applies to: SEN65

Description: Returns the measured values. The command **Get Data Ready** can be used to check if new data is available since the last read operation. If no new data is available, the previous values will be returned. If no data is available at all (e.g. measurement not running for at least one second), all values will be at their upper limit (0xFFFF for `uint16`, 0x7FFF for `int16`).

Read Measured Values SEN65			
Command ID	0x0446		
Available in	Measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	24 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Mass Concentration PM1.0: `uint16`
	1	LSB	Value is scaled with factor 10: PM1.0 [$\mu g/m^3$] = value / 10
	2	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	3	MSB	Mass Concentration PM2.5: `uint16`
	4	LSB	Value is scaled with factor 10: PM2.5 [$\mu g/m^3$] = value / 10
	5	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	6	MSB	Mass Concentration PM4.0: `uint16`
	7	LSB	Value is scaled with factor 10: PM4.0 [$\mu g/m^3$] = value / 10
	8	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	9	MSB	Mass Concentration PM10.0: `uint16`
	10	LSB	Value is scaled with factor 10: PM10.0 [$\mu g/m^3$] = value / 10
	11	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	12	MSB	Ambient Humidity: `int16`
	13	LSB	Value is scaled with factor 100: RH [%] = value / 100
	14	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	15	MSB	Ambient Temperature: `int16`
	16	LSB	Value is scaled with factor 200: T [°C] = value / 200
	17	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	18	MSB	VOC Index: `int16`
	19	LSB	Value is scaled with factor 10: VOC Index = value / 10
	20	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	21	MSB	NOx Index: `int16`
	22	LSB	Value is scaled with factor 10: NOx Index = value / 10
	23	CRC	*Note: If this value is unknown, 0x7FFF is returned. During the first 10..11 seconds after power-on or device reset, this value will be 0x7FFF as well.*

Table 32. Read measured values SEN65 I^2C command description

4.8.7 Read Measured Values SEN66

Applies to: SEN66

Description: Returns the measured values. The command **Get Data Ready** can be used to check if new data is available since the last read operation. If no new data is available, the previous values will be returned. If no data is available at all (e.g. measurement not running for at least one second), all values will be at their upper limit (0xFFFF for `uint16`, 0x7FFF for `int16`).

Read Measured Values SEN66			
Command ID	0x0300		
Available in	Measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	27 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Mass Concentration PM1.0: `uint16`
	1	LSB	Value is scaled with factor 10: PM1.0 [$\mu g/m^3$] = value / 10
	2	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	3	MSB	Mass Concentration PM2.5: `uint16`
	4	LSB	Value is scaled with factor 10: PM2.5 [$\mu g/m^3$] = value / 10
	5	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	6	MSB	Mass Concentration PM4.0: `uint16`
	7	LSB	Value is scaled with factor 10: PM4.0 [$\mu g/m^3$] = value / 10
	8	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	9	MSB	Mass Concentration PM10.0: `uint16`
	10	LSB	Value is scaled with factor 10: PM10.0 [$\mu g/m^3$] = value / 10
	11	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	12	MSB	Ambient Humidity: `int16`
	13	LSB	Value is scaled with factor 100: RH [%] = value / 100
	14	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	15	MSB	Ambient Temperature: `int16`
	16	LSB	Value is scaled with factor 200: T [°C] = value / 200
	17	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	18	MSB	VOC Index: `int16`
	19	LSB	Value is scaled with factor 10: VOC Index = value / 10
	20	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	21	MSB	NOx Index: `int16`
	22	LSB	Value is scaled with factor 10: NOx Index = value / 10
	23	CRC	*Note: If this value is unknown, 0x7FFF is returned. During the first 10..11 seconds after power-on or device reset, this value will be 0x7FFF as well.*
	24	MSB	CO2: `uint16`
	25	LSB	CO2 concentration [ppm]
	26	CRC	*Note: If this value is unknown, 0xFFFF is returned. During the first 5..6 seconds after measurement start, this value will be 0xFFFF as well.*

Table 33. Read measured values SEN66 I^2C command description

4.8.8 Read Measured Values SEN68

Applies to: SEN68

Description: Returns the measured values. The command **Get Data Ready** can be used to check if new data is available since the last read operation. If no new data is available, the previous values will be returned. If no data is available at all (e.g. measurement not running for at least one second), all values will be at their upper limit (0xFFFF for `uint16`, 0x7FFF for `int16`).

Read Measured Values SEN68			
Command ID	0x0467		
Available in	Measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	27 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Mass Concentration PM1.0: `uint16`
	1	LSB	Value is scaled with factor 10: PM1.0 [$\mu g/m^3$] = value / 10
	2	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	3	MSB	Mass Concentration PM2.5: `uint16`
	4	LSB	Value is scaled with factor 10: PM2.5 [$\mu g/m^3$] = value / 10
	5	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	6	MSB	Mass Concentration PM4.0: `uint16`
	7	LSB	Value is scaled with factor 10: PM4.0 [$\mu g/m^3$] = value / 10
	8	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	9	MSB	Mass Concentration PM10.0: `uint16`
	10	LSB	Value is scaled with factor 10: PM10.0 [$\mu g/m^3$] = value / 10
	11	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	12	MSB	Ambient Humidity: `int16`
	13	LSB	Value is scaled with factor 100: RH [%] = value / 100
	14	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	15	MSB	Ambient Temperature: `int16`
	16	LSB	Value is scaled with factor 200: T [°C] = value / 200
	17	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	18	MSB	VOC Index: `int16`
	19	LSB	Value is scaled with factor 10: VOC Index = value / 10
	20	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	21	MSB	NOx Index: `int16`
	22	LSB	Value is scaled with factor 10: NOx Index = value / 10
	23	CRC	*Note: If this value is unknown, 0x7FFF is returned. During the first 10..11 seconds after power-on or device reset, this value will be 0x7FFF as well.*
	24	MSB	Formaldehyde: `uint16`
	25	LSB	Value is scaled with factor 10: HCHO [ppb] = value / 10
	26	CRC	*Note: If this value is unknown, 0xFFFF is returned. During the first 60 seconds after the first measurement start after power-on or device reset, this value will be 0xFFFF as well.*

Table 34. Read measured values SEN68 I²C command description

4.8.9 Read Measured Values SEN69C

Applies to: SEN69C

Description: Returns the measured values. The command **Get Data Ready** can be used to check if new data is available since the last read operation. If no new data is available, the previous values will be returned. If no data is available at all (e.g. measurement not running for at least one second), all values will be at their upper limit (0xFFFF for `uint16`, 0x7FFF for `int16`).

Read Measured Values SEN69C			
Command ID	0x04B5		
Available in	Measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	30 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Mass Concentration PM1.0: `uint16`
	1	LSB	Value is scaled with factor 10: PM1.0 [$\mu g/m^3$] = value / 10
	2	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	3	MSB	Mass Concentration PM2.5: `uint16`
	4	LSB	Value is scaled with factor 10: PM2.5 [$\mu g/m^3$] = value / 10
	5	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	6	MSB	Mass Concentration PM4.0: `uint16`
	7	LSB	Value is scaled with factor 10: PM4.0 [$\mu g/m^3$] = value / 10
	8	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	9	MSB	Mass Concentration PM10.0: `uint16`
	10	LSB	Value is scaled with factor 10: PM10.0 [$\mu g/m^3$] = value / 10
	11	CRC	*Note: If this value is unknown, 0xFFFF is returned.*
	12	MSB	Ambient Humidity: `int16`
	13	LSB	Value is scaled with factor 100: RH [%] = value / 100
	14	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	15	MSB	Ambient Temperature: `int16`
	16	LSB	Value is scaled with factor 200: T [°C] = value / 200
	17	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	18	MSB	VOC Index: `int16`
	19	LSB	Value is scaled with factor 10: VOC Index = value / 10
	20	CRC	*Note: If this value is unknown, 0x7FFF is returned.*
	21	MSB	NOx Index: `int16`
	22	LSB	Value is scaled with factor 10: NOx Index = value / 10
	23	CRC	*Note: If this value is unknown, 0x7FFF is returned. During the first 10..11 seconds after power-on or device reset, this value will be 0x7FFF as well.*
	24	MSB	Formaldehyde: `uint16`
	25	LSB	Value is scaled with factor 10: HCHO [ppb] = value / 10
	26	CRC	*Note: If this value is unknown, 0xFFFF is returned. During the first 60 seconds after the first measurement start after power-on or device reset, this value will be 0xFFFF as well.*
	27	MSB	CO2: `int16`
	28	LSB	CO2 concentration [ppm]
	29	CRC	*Note: If this value is unknown, 0x7FFF is returned. During the first 22..24 seconds starting a measurement, this value will be 0x7FFF.*

Table 35. Read measured values SEN69C I^2C command description

4.8.10 Read Measured Raw Values SEN62, SEN63C

Applies to: SEN62, SEN63C

Description: Returns the measured raw values. The command **Get Data Ready** can be used to check if new data is available since the last read operation. If no new data is available, the previous values will be returned. If no data is available at all (e.g. measurement not running for at least one second), all values will be at their upper limit (0x7FFF for `int16`).

Read Measured Raw Values SEN62, SEN63C			
Command ID	0x0492		
Available in	Measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	6 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Raw Humidity: `int16` Value is scaled with factor 100: RH [%] = value / 100 *Note: If this value is unknown, 0x7FFF is returned.*
	1	LSB	
	2	CRC	
	3	MSB	Raw Temperature: `int16` Value is scaled with factor 200: T [°C] = value / 200 *Note: If this value is unknown, 0x7FFF is returned.*
	4	LSB	
	5	CRC	

Table 36. Read measured raw values SEN62, SEN63C I^2C command description

4.8.11 Read Measured Raw Values SEN65, SEN68, SEN69C

Applies to: SEN65, SEN68, SEN69C

Description: Returns the measured raw values. The command **Get Data Ready** can be used to check if new data is available since the last read operation. If no new data is available, the previous values will be returned. If no data is available at all (e.g. measurement not running for at least one second), all values will be at their upper limit (0xFFFF for `uint16`, 0x7FFF for `int16`).

Read Measured Raw Values SEN65, SEN68, SEN69C			
Command ID	0x0455		
Available in	Measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	12 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Raw Humidity: `int16` Value is scaled with factor 100: RH [%] = value / 100 *Note: If this value is unknown, 0x7FFF is returned.*
	1	LSB	
	2	CRC	
	3	MSB	Raw Temperature: `int16` Value is scaled with factor 200: T [°C] = value / 200 *Note: If this value is unknown, 0x7FFF is returned.*
	4	LSB	
	5	CRC	
	6	MSB	Raw VOC: `uint16` Raw measured VOC ticks without scale factor. *Note: If this value is unknown, 0xFFFF is returned.*
	7	LSB	
	8	CRC	
	9	MSB	Raw NOx: `uint16` Raw measured NOx ticks without scale factor. *Note: If this value is unknown, 0xFFFF is returned. During the first 10..11 seconds after power-on or device reset, this value will be 0xFFFF as well.*
	10	LSB	
	11	CRC	

Table 37. Read measured raw values SEN65, SEN68, SEN69C I^2C command description

4.8.12 Read Measured Raw Values SEN66

Applies to: SEN66

Description: Returns the measured raw values. The command **Get Data Ready** can be used to check if new data is available since the last read operation. If no new data is available, the previous values will be returned. If no data is available at all (e.g. measurement not running for at least one second), all values will be at their upper limit (0xFFFF for `uint16`, 0x7FFF for `int16`).

Read Measured Raw Values SEN66			
Command ID	0x0405		
Available in	Measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	15 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Raw Humidity: `int16` Value is scaled with factor 100: RH [%] = value / 100 *Note: If this value is unknown, 0x7FFF is returned.*
	1	LSB	
	2	CRC	
	3	MSB	Raw Temperature: `int16` Value is scaled with factor 200: T [°C] = value / 200 *Note: If this value is unknown, 0x7FFF is returned.*
	4	LSB	
	5	CRC	
	6	MSB	Raw VOC: `uint16` Raw measured VOC ticks without scale factor. *Note: If this value is unknown, 0xFFFF is returned.*
	7	LSB	
	8	CRC	
	9	MSB	Raw NOx: `uint16` Raw measured NOx ticks without scale factor. *Note: If this value is unknown, 0xFFFF is returned. During the first 10..11 seconds after power-on or device reset, this value will be 0xFFFF as well.*
	10	LSB	
	11	CRC	
	12	MSB	Raw CO2: `uint16` Not interpolated CO2 concentration [ppm] updated every five seconds. *Note: If this value is unknown, 0xFFFF is returned. During the first 5..6 seconds after measurement start, this value will be 0xFFFF as well.*
	13	LSB	
	14	CRC	

Table 38. Read measured raw values SEN66 I^2C command description

4.8.13 Read Number Concentration Values

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: Returns the measured number concentration values. The command **Get Data Ready** can be used to check if new data is available since the last read operation. If no new data is available, the previous values will be returned. If no data is available at all (e.g. measurement not running for at least one second), all values will be at their upper limit (0xFFFF for `uint16`).

Read Number Concentration Values			
Command ID	0x0316		
Available in	Measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	15 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Number Concentration PM0.5: `uint16` Value is scaled with factor 10: PM0.5 [particles/cm^3] = value / 10 *Note: If this value is unknown, 0xFFFF is returned.*
	1	LSB	
	2	CRC	
	3	MSB	Number Concentration PM1.0: `uint16` Value is scaled with factor 10: PM1.0 [particles/cm^3] = value / 10 *Note: If this value is unknown, 0xFFFF is returned.*
	4	LSB	
	5	CRC	
	6	MSB	Number Concentration PM2.5: `uint16` Value is scaled with factor 10: PM2.5 [particles/cm^3] = value / 10 *Note: If this value is unknown, 0xFFFF is returned.*
	7	LSB	
	8	CRC	
	9	MSB	Number Concentration PM4.0: `uint16` Value is scaled with factor 10: PM4.0 [particles/cm^3] = value / 10 *Note: If this value is unknown, 0xFFFF is returned.*
	10	LSB	
	11	CRC	
	12	MSB	Number Concentration PM10.0: `uint16` Value is scaled with factor 10: PM10.0 [particles/cm^3] = value / 10 *Note: If this value is unknown, 0xFFFF is returned.*
	13	LSB	
	14	CRC	

Table 39. Read number concentration values I^{2}C command description

4.8.14 Set Temperature Offset Parameters

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: This command allows to compensate temperature effects of the design-in at customer side by applying custom temperature offsets to the ambient temperature. The compensated ambient temperature is calculated as follows:

$$T_{Measured\_Compensated} = T_{Measured} + (Slope * T_{Measured}) + C_{Offset}$$

Where $Slope$ and C_{Offset} are the values set with this command, smoothed with the specified time constant. All temperatures ($T_{Measured\_Compensated}$, $T_{Measured}$ and C_{Offset}) are represented in °C. There are 5 temperature offset slots available that all contribute additively to $T_{Measured\_Compensated}$. The default values for the temperature offset parameters are all zero, meaning that $T_{Measured\_Compensated}$ is equal to $T_{Measured}$ by default. For more details on how to compensate the temperature on the SEN6x platform, refer to "SEN6x – Temperature Acceleration and Compensation Instructions" [3].

Note: This configuration is volatile, i.e. the parameters will be reverted to their default value of zero after a device reset.

<table>
<tr><th colspan="4">Set Temperature Offset Parameters</th></tr>
<tr><td>Command ID</td><td colspan="3">0x60B2</td></tr>
<tr><td>Available in</td><td colspan="3">Idle and measurement mode</td></tr>
<tr><td>Execution Time</td><td colspan="3">20 ms</td></tr>
<tr><td>Max. RX Data With CRC</td><td colspan="3">0 Bytes</td></tr>
<tr><td rowspan="13">TX Data</td><td colspan="2">Byte #</td><td>Description</td></tr>
<tr><td>0</td><td>MSB</td><td rowspan="3">Offset: <code>int16</code>
Constant temperature offset scaled with factor 200 (T [°C] = value / 200).</td></tr>
<tr><td>1</td><td>LSB</td></tr>
<tr><td>2</td><td>CRC</td></tr>
<tr><td>3</td><td>MSB</td><td rowspan="3">Slope: <code>int16</code>
Normalized temperature offset slope scaled with factor 10000 (applied factor = value / 10000).</td></tr>
<tr><td>4</td><td>LSB</td></tr>
<tr><td>5</td><td>CRC</td></tr>
<tr><td>6</td><td>MSB</td><td rowspan="3">Time Constant: <code>uint16</code>
The time constant determines how fast the new slope and offset will be applied. After the specified value in seconds, 63% of the new slope and offset are applied. A time constant of zero means the new values will be applied immediately (within the next measure interval of 1 second).</td></tr>
<tr><td>7</td><td>LSB</td></tr>
<tr><td>8</td><td>CRC</td></tr>
<tr><td>9</td><td>MSB</td><td rowspan="3">Slot: <code>uint16</code>
The temperature offset slot to be modified. Valid values are 0 .. 4. If the value is outside this range, the parameters will not be applied.
Note: A total of five slots are available. Each slot represents one temperature offset. Usually slot 0 is used to compensate for the base self-heating and the other slots allow to compensate for additional heating of components like screens, Wi-Fi modules, etc. that can be switched on and off independently.</td></tr>
<tr><td>10</td><td>LSB</td></tr>
<tr><td>11</td><td>CRC</td></tr>
<tr><td>RX Data</td><td colspan="3">None</td></tr>
</table>

Table 40. Set temperature offset parameters I²C command description

4.8.15 Set Temperature Acceleration Parameters

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: This command allows to set custom temperature acceleration parameters of the RH/T engine. It overwrites the default temperature acceleration parameters of the RH/T engine with custom values.

For more details on how to compensate the temperature on the SEN6x platform, refer to "SEN6x – Temperature Acceleration and Compensation" [3].

Note: This configuration is volatile, i.e. the parameters will be reverted to their default values after a device reset.

Set Temperature Acceleration Parameters			
Command ID	0x6100		
Available in	Idle mode		
Execution Time	20 ms		
Max. RX Data With CRC	0 Bytes		
TX Data	Byte #		Description
	0	MSB	K: `uint16` Filter constant K scaled with factor 10 (K = value / 10).
	1	LSB	
	2	CRC	
	3	MSB	P: `uint16` Filter constant P scaled with factor 10 (P = value / 10).
	4	LSB	
	5	CRC	
	6	MSB	T1: `uint16` Time constant T1 scaled with factor 10 (T1 [s] = value / 10).
	7	LSB	
	8	CRC	
	9	MSB	T2: `uint16` Time constant T2 scaled with factor 10 (T2 [s] = value / 10).
	10	LSB	
	11	CRC	
RX Data	None		

Table 41. Set temperature acceleration parameters I^2C command description

4.8.16 Get Product Name

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: Gets the product name from the device.

Get Product Name			
Command ID	0xD014		
Available in	Idle and measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	48 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	Char 0	Product Name: `string<32>` Null-terminated ASCII string containing the product name. Up to 32 characters can be read from the device.
	1	Char 1	
	2	CRC	
	...	...	
	45	Char 30	
	46	Char 31	
	47	CRC	

Table 42. Get product name I²C command description

4.8.17 Get Serial Number

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: Gets the serial number from the device.

Get Serial Number			
Command ID	0xD033		
Available in	Idle and measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	48 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	Char 0	Serial Number: `string<32>` Null-terminated ASCII string containing the serial number. Up to 32 characters can be read from the device.
	1	Char 1	
	2	CRC	
	...	...	
	45	Char 30	
	46	Char 31	
	47	CRC	

Table 43. Get serial number I²C command description

4.8.18 Read Device Status

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: Reads the current device status.

Use this command to get detailed information about the device status. The device status is encoded in flags. Each device status flag represents a single bit in a 32-bit integer value. If more than one error is present, the device status register value is the sum of the corresponding flag values. For details about the available flags, refer to the **Device Status Register** documentation.

Note: The status flags of type "Error" are sticky, i.e. they are not cleared automatically even if the error condition no longer exists. So, they can only be cleared manually with **Read And Clear Device Status** or through a reset, either by calling **Device Reset** or through a power cycle**.** All other flags are not sticky, i.e. they are cleared automatically if the trigger condition disappears.

Read Device Status			
Command ID	0xD206		
Available in	Idle and measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	6 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Device Status: `uint32` Device status (32 flags as an integer value). For details, please refer to the **Device Status Register** documentation.
	1	-	
	2	CRC	
	3	-	
	4	LSB	
	5	CRC	

Table 44. Read device status I²C command description

4.8.19 Read And Clear Device Status

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: Reads the current device status (like command **Read Device Status**) and afterwards clears all flags.

Read And Clear Device Status			
Command ID	0xD210		
Available in	Idle and measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	6 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Device Status: `uint32` Device status (32 flags as an integer value) before clearing it. For details, please refer to the **Device Status Register** documentation.
	1	-	
	2	CRC	
	3	-	
	4	LSB	
	5	CRC	

Table 45. Read and clear device status I²C command description

4.8.20 Get Version

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: Gets the version information for the firmware.

Get Version			
Command ID	0xD100		
Available in	Idle and measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	12 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	-	Firmware Major: `uint8` Firmware major version number.
	1	-	Firmware Minor: `uint8` Firmware minor version number.
	2	CRC	CRC for the previous two bytes.

Table 46. Get version I²C command description

4.8.21 Device Reset

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: Executes a reset on the device. This has the same effect as a power cycle.

Device Reset	
Command ID	0xD304
Available in	Idle mode
Execution Time	1200 ms
Max. RX Data With CRC	0 Bytes
TX Data	None
RX Data	None

Table 47. Device reset I²C command description

4.8.22 Start Fan Cleaning

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: This command triggers fan cleaning. The fan is set to the maximum speed for 10 seconds and then automatically stopped. Wait at least 10s after this command before starting a measurement.

Start Fan Cleaning	
Command ID	0x5607
Available in	Idle mode
Execution Time	20 ms
Max. RX Data With CRC	0 Bytes
TX Data	None
RX Data	None

Table 48. Start fan cleaning I²C command description

4.8.23 Activate SHT Heater

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: This command allows you to use the inbuilt heater in SHT sensor to reverse creep at high humidity. This command activates the SHT sensor heater with 200mW for 1s. The heater is then automatically deactivated again. For firmware versions with an *Execution Time* of 20ms in the table below, the **Get SHT Heater Measurements** command can be polled to check whether the heating is finished to trigger another cycle to maximize the duty cycle. Older firmware version do not yet support **Get SHT Heater Measurements.**

Wait at least 20s after this command before starting a measurement to get coherent temperature values (heating consequence to disappear).

Activate SHT Heater				
Command ID	0x6765			
Available in	Idle mode			
Execution Time	Firmware Version	SEN62	>=6.0	20 ms
		SEN63C	>=5.0	
		SEN65	>=5.0	
		SEN66	>=4.0	
		SEN68	>=7.0	
		SEN69C	>=9.0	
	Older Firmware Versions			1300ms
Max. RX Data With CRC	0 Bytes			
TX Data	None			
RX Data	None			

Table 49. Activate SHT heater I^2C command description

4.8.24 Get SHT Heater Measurements

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

Description: Get the measurement values when the SHT sensor heating is finished.

Note: This command is only available from the *Firmware Version* specified in the table below. It must be used after the **Activate SHT Heater** command. The command can be queried every 50ms to check if the heating cycle is finished and measurements are available.

<table>
<tr><th colspan="5">Get SHT Heater Measurements</th></tr>
<tr><td>Command ID</td><td colspan="4">0x6790</td></tr>
<tr><td rowspan="6">Firmware Version</td><td colspan="2">SEN62</td><td colspan="2">>=6.0</td></tr>
<tr><td colspan="2">SEN63C</td><td colspan="2">>=5.0</td></tr>
<tr><td colspan="2">SEN65</td><td colspan="2">>=5.0</td></tr>
<tr><td colspan="2">SEN66</td><td colspan="2">>=4.0</td></tr>
<tr><td colspan="2">SEN68</td><td colspan="2">>=7.0</td></tr>
<tr><td colspan="2">SEN69C</td><td colspan="2">>= 9.0</td></tr>
<tr><td>Available in</td><td colspan="4">Idle mode</td></tr>
<tr><td>Execution Time</td><td colspan="4">20 ms</td></tr>
<tr><td>Max. RX Data With CRC</td><td colspan="4">6 Bytes</td></tr>
<tr><td>TX Data</td><td colspan="4">None</td></tr>
<tr><td rowspan="7">RX Data</td><td colspan="2">Byte #</td><td colspan="2">Description</td></tr>
<tr><td>0</td><td>MSB</td><td colspan="2" rowspan="3">SHT Relative Humidity: <code>int16</code>
If the SHT heating is completed, this value indicates the scaled relative humidity of the SHT4x sensor.
Value is scaled with factor 100: RH [%] = value / 100
Note: If this value is not available, 0x7FFF is returned.</td></tr>
<tr><td>1</td><td>LSB</td></tr>
<tr><td>2</td><td>CRC</td></tr>
<tr><td>3</td><td>MSB</td><td colspan="2" rowspan="3">SHT Temperature: <code>int16</code>
If the SHT heating is completed, this value indicates the scaled temperature of the SHT4x sensor.
Value is scaled with factor 200: T [°C] = value / 200
Note: If this value is not available, 0x7FFF is returned.</td></tr>
<tr><td>4</td><td>LSB</td></tr>
<tr><td>5</td><td>CRC</td></tr>
</table>

Table 50. Get SHT Heater Measurements I^2C command description

4.8.25 Get VOC Algorithm Tuning Parameters

Applies to: SEN65, SEN66, SEN68, SEN69C

Description: Gets the parameters to customize the VOC algorithm. For more information on what the parameters below do, refer to Sensirion's VOC Index for Indoor Air Applications [4].

Get VOC Algorithm Tuning Parameters			
Command ID	0x60D0		
Available in	Idle mode		
Execution Time	20 ms		
Max. RX Data With CRC	18 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Index Offset: `int16` VOC index representing typical (average) conditions.
	1	LSB	
	2	CRC	
	3	MSB	Learning Time Offset Hours: `int16` Time constant to estimate the VOC algorithm offset from the history in hours. Past events will be forgotten after about twice the learning time.
	4	LSB	
	5	CRC	
	6	MSB	Learning Time Gain Hours: `int16` Time constant to estimate the VOC algorithm gain from the history in hours. Past events will be forgotten after about twice the learning time.
	7	LSB	
	8	CRC	
	9	MSB	Gating Max Duration Minutes: `int16` Maximum duration of gating in minutes (freeze of estimator during high VOC index signal). Zero disables the gating.
	10	LSB	
	11	CRC	
	12	MSB	Std Initial: `int16` Initial estimate for standard deviation. Lower value boosts events during initial learning period but may result in larger device-to-device variations.
	13	LSB	
	14	CRC	
	15	MSB	Gain Factor: `int16` Gain factor to amplify or to attenuate the VOC index output.
	16	LSB	
	17	CRC	

Table 51. Get VOC algorithm tuning parameters I^2C command description

4.8.26 Set VOC Algorithm Tuning Parameters

Applies to: SEN65, SEN66, SEN68, SEN69C

Description: Sets the parameters to customize the VOC algorithm. It has no effect if at least one parameter is outside the specified range. For more information on what the parameters below do, refer to Sensirion's VOC Index for Indoor Air Applications [4].

Note: This configuration is volatile, i.e. the parameters will be reverted to their default values after a device reset.

Set VOC Algorithm Tuning Parameters			
Command ID	0x60D0		
Available in	Idle mode		
Execution Time	20 ms		
Max. RX Data With CRC	0 Bytes		
TX Data	Byte #		Description
	0	MSB	Index Offset: `int16` Range: `1..250` VOC index representing typical (average) conditions. Allowed values are in range 1..250. The default value is 100.
	1	LSB	
	2	CRC	
	3	MSB	Learning Time Offset Hours: `int16` Range: `1..1000` Time constant to estimate the VOC algorithm offset from the history in hours. Past events will be forgotten after about twice the learning time. Allowed values are in range 1..1000. The default value is 12 hours.
	4	LSB	
	5	CRC	
	6	MSB	Learning Time Gain Hours: `int16` Range: `1..1000` Time constant to estimate the VOC algorithm gain from the history in hours. Past events will be forgotten after about twice the learning time. Allowed values are in range 1..1000. The default value is 12 hours.
	7	LSB	
	8	CRC	
	9	MSB	Gating Max Duration Minutes: `int16` Range: `0..3000` Maximum duration of gating in minutes (freeze of estimator during high VOC index signal). Set to zero to disable the gating. Allowed values are in range 0..3000. The default value is 180 minutes.
	10	LSB	
	11	CRC	
	12	MSB	Std Initial: `int16` Range: `10..5000` Initial estimate for standard deviation. Lower value boosts events during initial learning period but may result in larger device-to-device variations. Allowed values are in range 10..5000. The default value is 50.
	13	LSB	
	14	CRC	
	15	MSB	Gain Factor: `int16` Range: `1..1000` Gain factor to amplify or to attenuate the VOC index output. Allowed values are in range 1..1000. The default value is 230.
	16	LSB	
	17	CRC	
RX Data	None		

Table 52. Set VOC algorithm tuning parameters I^2C command description

4.8.27 Get VOC Algorithm State

Applies to: SEN65, SEN66, SEN68, SEN69C

Description: Allows backup of the VOC algorithm state to resume operation after a power cycle or device reset, skipping initial learning phase. By default, the VOC Engine is reset, and the algorithm state is retained if a measurement is stopped and started again. If the VOC algorithm state shall be reset, a device reset, or a power cycle can be executed.

Gets the current VOC algorithm state. This data can be used to restore the state with the **Set VOC Algorithm State** command after a short power cycle or device reset.
This command can be used either in measurement mode or in idle mode (which will then return the state at the time when the measurement was stopped). In measurement mode, the state can be read each measure interval to always have the latest state available, even in case of a sudden power loss.

<table>
<tr><th colspan="4">Get VOC Algorithm State</th></tr>
<tr><td>Command ID</td><td colspan="3">0x6181</td></tr>
<tr><td>Available in</td><td colspan="3">Idle and measurement mode</td></tr>
<tr><td>Execution Time</td><td colspan="3">20 ms</td></tr>
<tr><td>Max. RX Data With CRC</td><td colspan="3">12 Bytes</td></tr>
<tr><td>TX Data</td><td colspan="3">None</td></tr>
<tr><td rowspan="9">RX Data</td><td colspan="2">Byte #</td><td>Description</td></tr>
<tr><td>0</td><td>Byte 0</td><td rowspan="8">State: <code>bytearray<8></code>
Current VOC algorithm state.</td></tr>
<tr><td>1</td><td>Byte 1</td></tr>
<tr><td>2</td><td>CRC</td></tr>
<tr><td>…</td><td>…</td></tr>
<tr><td>9</td><td>Byte 6</td></tr>
<tr><td>10</td><td>Byte 7</td></tr>
<tr><td>11</td><td>CRC</td></tr>
</table>

Table 53. Get VOC algorithm state I^2C command description

4.8.28 Set VOC Algorithm State

Applies to: SEN65, SEN66, SEN68, SEN69C

Description: Allows restoration of the VOC algorithm state to resume operation after a power cycle or device reset, skipping initial learning phase. By default, the VOC Engine is reset, and the algorithm state is retained if a measurement is stopped and started again. If the VOC algorithm state shall be reset, a device reset, or a power cycle can be executed.

Sets the VOC algorithm state previously received with the **Get VOC Algorithm State** command. This command is only available in idle mode and the state will be applied only once when starting the next measurement. In measurement mode, this command has no effect.

Note: This configuration is volatile, i.e. the parameters will be reverted to their default values after a device reset.

<table>
<tr><th colspan="4">Set VOC Algorithm State</th></tr>
<tr><td>Command ID</td><td colspan="3">0x6181</td></tr>
<tr><td>Available in</td><td colspan="3">Idle mode</td></tr>
<tr><td>Execution Time</td><td colspan="3">20 ms</td></tr>
<tr><td>Max. RX Data With CRC</td><td colspan="3">0 Bytes</td></tr>
<tr><td rowspan="9">TX Data</td><td colspan="2">Byte #</td><td>Description</td></tr>
<tr><td>0</td><td>Byte 0</td><td rowspan="8">State: <code>bytearray<8></code>
VOC algorithm state to restore.</td></tr>
<tr><td>1</td><td>Byte 1</td></tr>
<tr><td>2</td><td>CRC</td></tr>
<tr><td>…</td><td>…</td></tr>
<tr><td>9</td><td>Byte 6</td></tr>
<tr><td>10</td><td>Byte 7</td></tr>
<tr><td>11</td><td>CRC</td></tr>
<tr><td>RX Data</td><td colspan="3">None</td></tr>
</table>

Table 54. Set VOC algorithm state I²C command description

4.8.29 Get NO_x Algorithm Tuning Parameters

Applies to: SEN65, SEN66, SEN68, SEN69C

Description: Gets the parameters to customize the NOx algorithm. For more information on what the parameters below do, refer to Sensirion's NOx Index for Indoor Air Applications [5].

Get NOx Algorithm Tuning Parameters			
Command ID	0x60E1		
Available in	Idle mode		
Execution Time	20 ms		
Max. RX Data With CRC	18 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Index Offset: `int16` NOx index representing typical (average) conditions.
	1	LSB	
	2	CRC	
	3	MSB	Learning Time Offset Hours: `int16` Time constant to estimate the NOx algorithm offset from the history in hours. Past events will be forgotten after about twice the learning time.
	4	LSB	
	5	CRC	
	6	MSB	Learning Time Gain Hours: `int16` The time constant to estimate the NOx algorithm gain from the history has no impact for NOx. This parameter is still in place for consistency reasons with the VOC tuning parameters command.
	7	LSB	
	8	CRC	
	9	MSB	Gating Max Duration Minutes: `int16` Maximum duration of gating in minutes (freeze of estimator during high NOx index signal). Zero disables the gating.
	10	LSB	
	11	CRC	
	12	MSB	Std Initial: `int16` The initial estimate for standard deviation has no impact for NOx. This parameter is still in place for consistency reasons with the VOC tuning parameters command.
	13	LSB	
	14	CRC	
	15	MSB	Gain Factor: `int16` Gain factor to amplify or to attenuate the NOx index output.
	16	LSB	
	17	CRC	

Table 55. Get NO_x algorithm tuning parameters I^2C command description

4.8.30 Set NO_x Algorithm Tuning Parameters

Applies to: SEN65, SEN66, SEN68, SEN69C

Description: Sets the parameters to customize the NOx algorithm. It has no effect if at least one parameter is outside the specified range. To check whether the parameters have been set successfully, use the **Get NOx Algorithm Tuning Parameters** command. For more information on what the parameters below do, refer to Sensirion's NOx Index for Indoor Air Applications [5].

Note: This configuration is volatile, i.e. the parameters will be reverted to their default values after a device reset.

Set NOx Algorithm Tuning Parameters			
Command ID	0x60E1		
Available in	Idle mode		
Execution Time	20 ms		
Max. RX Data With CRC	0 Bytes		
TX Data	Byte #		Description
	0	MSB	Index Offset: `int16` Range: `1..250` NOx index representing typical (average) conditions. Allowed values are in range 1..250. The default value is 1.
	1	LSB	
	2	CRC	
	3	MSB	Learning Time Offset Hours: `int16` Range: `1..1000` Time constant to estimate the NOx algorithm offset from the history in hours. Past events will be forgotten after about twice the learning time. Allowed values are in range 1..1000. The default value is 12 hours.
	4	LSB	
	5	CRC	
	6	MSB	Learning Time Gain Hours: `int16` Range: `1..1000` The time constant to estimate the NOx algorithm gain from the history has no impact for NOx. This parameter is still in place for consistency reasons with the VOC tuning parameters command. This parameter must always be set to 12 hours.
	7	LSB	
	8	CRC	
	9	MSB	Gating Max Duration Minutes: `int16` Range: `0..3000` Maximum duration of gating in minutes (freeze of estimator during high NOx index signal). Set to zero to disable the gating. Allowed values are in range 0..3000. The default value is 720 minutes.
	10	LSB	
	11	CRC	
	12	MSB	Std Initial: `int16` Range: `10..5000` The initial estimate for standard deviation parameter has no impact for NOx. This parameter is still in place for consistency reasons with the VOC tuning parameters command. This parameter must always be set to 50.
	13	LSB	
	14	CRC	
	15	MSB	Gain Factor: `int16` Range: `1..1000` Gain factor to amplify or to attenuate the NOx index output. Allowed values are in range 1..1000. The default value is 230.
	16	LSB	
	17	CRC	
RX Data	None		

Table 56. Set NO_x algorithm tuning parameters I^2C command description

4.8.31 Perform Forced CO_2 Recalibration

Applies to: SEN63C, SEN66, SEN69C

Description: Execute the forced recalibration (FRC) of the CO_2 signal. To successfully conduct an accurate FRC, the following steps need to be taken:

1. Start a measurement with the command **Start Continuous Measurement** and operate the sensor for at least 3 minutes in an environment with homogenous and constant CO2 concentration. If applicable, the reference value for altitude or pressure compensation must be provided to the sensor beforehand with the command **Set Sensor Altitude** or **Set Ambient Pressure** respectively.
2. Stop the measurement with the command **Stop Measurement** and wait at least 1400ms.
3. Issue the **Perform Forced CO2 Recalibration** command with the reference CO_2 concentration that the sensor should be set to. The recalibration procedure will take about 500 ms to complete, during which time no other functions can be executed. A return value of 0xFFFF indicates that the FRC has failed

Note: This configuration is persistent, i.e. the parameters will be retained during a device reset or power cycle.

Perform Forced CO_2 Recalibration			
Command ID	0x6707		
Available in	Idle mode		
Execution Time	500 ms		
Max. RX Data With CRC	3 Bytes		
TX Data	Byte #		Description
	0	MSB	Reference CO_2 Concentration: `uint16` Reference CO_2 concentration [ppm] of the test setup.
	1	LSB	
	2	CRC	
RX Data	Byte #		Description
	0	MSB	Correction: `uint16` Correction value as received from the CO_2 sensor [ppm CO_2]. FRC correction [ppm CO_2] is return value - 0x8000, if the recalibration has failed this value is 0xFFFF.
	1	LSB	
	2	CRC	

Table 57. Perform forced CO_2 recalibration I^2C command description

4.8.32 Perform CO_2 Sensor Factory Reset

Applies to: SEN63C, SEN66, SEN69C

Description: This command resets all CO2 sensor configuration settings stored in the EEPROM and erases the forced recalibration (FRC) and automatic self-calibration (ASC) algorithm history of the CO2 sensor, restarting the bypass phase. Refer to the datasheet of the STCC4 for more information [6].

Perform CO_2 Sensor Factory Reset		
Command ID	0x6754	
Available in	Idle Mode	
Firmware Version	SEN63C, SEN69C	Available in all versions
	SEN66	>=1.2
Execution Time	1400 ms	
Max. RX Data With CRC	0 Bytes	
TX Data	None	
RX Data	None	

Table 58. Get CO_2 sensor automatic self-calibration I^2C command description

4.8.33 Get CO_2 Sensor Automatic Self Calibration

Applies to: SEN63C, SEN66, SEN69C

Description: Gets the status of the CO_2 sensor automatic self-calibration (ASC). The CO_2 sensor supports automatic self-calibration (ASC) for long-term stability of the CO_2 output. This feature can be enabled or disabled. By default, it is enabled.

Get CO_2 Sensor Automatic Self Calibration			
Command ID	0x6711		
Available in	Idle mode		
Execution Time	20 ms		
Max. RX Data With CRC	3 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0		Padding: `uint8` Padding byte, always 0x00.
	1		Status: `bool` Is set true (0x01) if the automatic self-calibration is enabled or false (0x00) if the automatic self-calibration is disabled.
	2	CRC	CRC for the previous two bytes.

Table 59. Get CO_2 sensor automatic self-calibration I^2C command description

4.8.34 Set CO_2 Sensor Automatic Self Calibration

Applies to: SEN63C, SEN66, SEN69C

Description: Sets the status of the CO_2 sensor automatic self-calibration (ASC). The CO_2 sensor supports automatic self-calibration (ASC) for long-term stability of the CO_2 output. This feature can be enabled or disabled. By default, it is enabled.

The automatic self-calibration can be disabled for testing under lab conditions where concentrations below 400ppm are expected, to avoid an alteration of the baseline. In the field, ASC must be enabled and exposure to fresh air (i.e. CO_2 concentration at 400 ppm) at least once per week is required to reach datasheet specifications

Note: This configuration is volatile, i.e. the parameters will be reverted to their default values after a device reset.

Set CO_2 Sensor Automatic Self Calibration			
Command ID	0x6711		
Available in	Idle mode		
Execution Time	20 ms		
Max. RX Data With CRC	0 Bytes		
TX Data	Byte #		Description
	0		Padding: `uint8` Padding byte, always 0x00.
	1		Status: `bool` Set to true (0x01) to enable or false (0x00) to disable the automatic CO2 measurement self-calibration feature.
	2	CRC	CRC for the previous two bytes.
RX Data	None		

Table 60. Set CO_2 sensor automatic self-calibration I^2C command description

4.8.35 Get Ambient Pressure

Applies to: SEN63C, SEN66, SEN69C

Description: Gets the ambient pressure value that was set with **Set Ambient Pressure**. The ambient pressure can be used for pressure compensation in the CO_2 sensor.

Get Ambient Pressure			
Command ID	0x6720		
Available in	Idle and measurement mode		
Execution Time	20 ms		
Max. RX Data With CRC	3 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Ambient Pressure: `uint16` Currently used ambient pressure [hPa] for pressure compensation.
	1	LSB	
	2	CRC	

Table 61. Get ambient pressure I^2C command description

4.8.36 Set Ambient Pressure

Applies to: SEN63C, SEN66, SEN69C

Description: Sets the ambient pressure value. The ambient pressure can be used for pressure compensation in the CO_2 sensor. Setting an ambient pressure overrides any pressure compensation based on a previously set sensor altitude. Use of this command is recommended for applications experiencing significant ambient pressure changes to ensure CO_2 sensor accuracy. Valid input values are between 700 to 1’200 hPa. The default value is 1013 hPa.

Note: This configuration is volatile, i.e. the parameters will be reverted to their default values after a device reset.

Set Ambient Pressure			
Description	Sets ambient pressure value.		
Available in	Idle and measurement mode		
Command ID	0x6720		
Execution Time	20 ms		
Max. RX Data With CRC	0 Bytes		
TX Data	Byte #		Description
	0	MSB	Ambient Pressure: `uint16` Ambient pressure [hPa] to be used for pressure compensation.
	1	LSB	
	2	CRC	
RX Data	None		

Table 62. Set ambient pressure I^2C command description

4.8.37 Get Sensor Altitude

Applies to: SEN63C, SEN66, SEN69C

Description: Gets the current sensor altitude. The sensor altitude can be used for pressure compensation in the CO_2 sensor.

Get Sensor Altitude			
Command ID	0x6736		
Available in	Idle mode		
Execution Time	20 ms		
Max. RX Data With CRC	3 Bytes		
TX Data	None		
RX Data	Byte #		Description
	0	MSB	Altitude: `uint16` Current sensor altitude [m].
	1	LSB	
	2	CRC	

Table 63. Get sensor altitude I^2C command description

4.8.38 Set Sensor Altitude

Applies to: SEN63C, SEN66, SEN69C

Description: Sets the current sensor altitude. The sensor altitude can be used for pressure compensation in the CO_2 sensor. The default sensor altitude value is set to 0 meters above sea level. Valid input values are between 0 and 3000m.

Note: This configuration is volatile, i.e. the parameters will be reverted to their default values after a device reset.

Set Sensor Altitude			
Command ID	0x6736		
Available in	Idle mode		
Execution Time	20 ms		
Max. RX Data With CRC	0 Bytes		
TX Data	Byte #		Description
	0	MSB	Altitude: `uint16` Sensor altitude [m], valid input between 0 and 3000m.
	1	LSB	
	2	CRC	
RX Data	None		

Table 64. Set sensor altitude I^2C command description

4.9 Checksum Calculation (CRC)

Applies to: SEN62, SEN63C, SEN65, SEN66, SEN68, SEN69C

The 8-bit CRC checksum transmitted after each data word is generated by a CRC algorithm. Its properties are displayed in **Table 65**. The CRC covers the contents of the two previously transmitted data bytes. To calculate the checksum, only these two previously transmitted data bytes are used. Note that command words are not followed by CRC.

Property	Value	Example code (C/C++)
Name	CRC-8-Dallas/Maxim	
Width	8 bits	
Protected Data	read and/or write data	
Polynomial	0x31 ($x^8+x^5+x^4+1$)	
Initialization	0xFF	
Reflect input	No	
Reflect output	No	
Final XOR	0x00	
Examples	CRC (0xBEEF) = 0x92	

```
#define CRC8_POLYNOMIAL 0x31
#define CRC8_INIT 0xFF

uint8_t sensirion_generate_crc(const uint8_t* data, uint16_t count) {
    uint16_t current_byte;
    uint8_t crc = CRC8_INIT;
    uint8_t crc_bit;
    /* calculates 8-Bit checksum with given polynomial */
    for (current_byte = 0; current_byte < count; ++current_byte) {
        crc ^= (data[current_byte]);
        for (crc_bit = 8; crc_bit > 0; --crc_bit) {
            if (crc & 0x80)
                crc = (crc << 1) ^ CRC8_POLYNOMIAL;
            else
                crc = (crc << 1);
        }
    }
    return crc;
}
```

Table 65. I^2C CRC properties

5 Technical Drawing

5.1 Package Outline

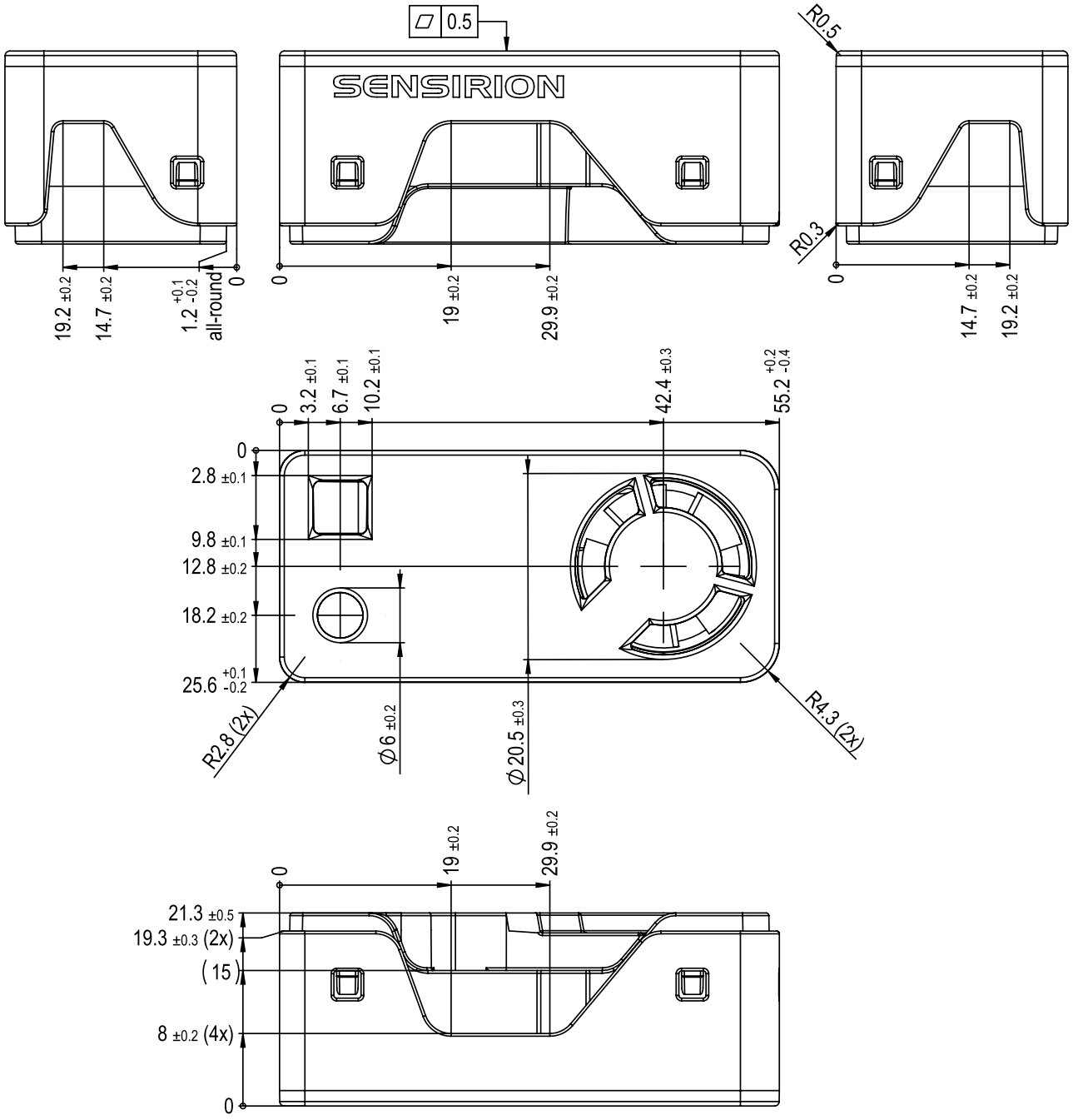


Figure 11. Technical Drawing of the SEN6x platform. All dimensions are in millimeters

5.2 Product Label

All SEN6x sensors include a 22mm x 8mm label as seen in **Figure 12**. For more information on the content, see **Table 66**.

Label Design	Label Content	Description
SEN6xx – SIN – T EEEEEEEE FFFFFFFF	QR Code	QR code containing the 16-digit HEX serial number
	SEN6xx-SIN-T	Material description as in **Table 67**
	EEEEEEEE	First 8 digits of the 16-digit HEX code
	FFFFFFFF	Last 8 digits of the 16-digit HEX code

Table 66. Label information

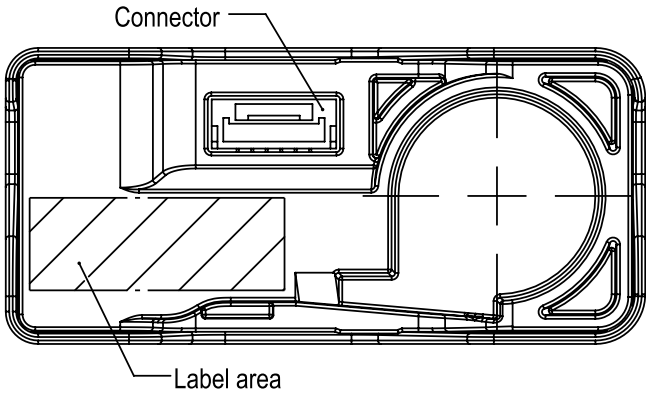


Figure 12. Label position on SEN6x

6 Ordering Information

Material Description	Material Number	Sensor Outputs	Quantity
SEN62-SIN-T	3.001.163	• Particulate Matter • Relative Humidity • Temperature	420pcs per box, 7 trays, 60pcs per tray
SEN63C-SIN-T	3.001.197	• Particulate Matter • Relative Humidity • Temperature • CO_2	
SEN65-SIN-T	3.001.203	• Particulate Matter • Relative Humidity • Temperature • VOC Index • NOx Index	
SEN66-SIN-T	3.001.030	• Particulate Matter • Relative Humidity • Temperature • VOC Index • NOx Index • CO_2	
SEN68-SIN-T	3.001.198	• Particulate Matter • Relative Humidity • Temperature • VOC Index • NOx Index • Formaldehyde	
SEN69C-SIN-T	3.001.418	• Particulate Matter • Relative Humidity • Temperature • VOC Index • NOx Index • Formaldehyde • CO_2	

Table 67. Ordering information

7 Bibliography

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8 Revision History

Date	Version	Pages	Changes
November 2024	V0.9	all	Initial public release
August 2025	V0.91	5-10, 16, 22, 25,38, 43, 44 52, 14, 50, 55, 57, 58, all	• Added references to default conditions for better context in section 1.1-1.6 • Aligned formatting across specification tables (**Table 2**, **Table 7**, **Table 11**, **Table 24**) • Slight adjustment to drift specification for improved accuracy (**Table 2**, **Table 3**) • Updated timing and response details for select parameters (**Table 4**, **Table 5**, **Table 7**) • Clarified sensor behavior and configuration notes (**4.8.1, Table , Table , 4.8.15, Activate SHT Heater, 4.8.26, 4.8.28, Set NOx Algorithm Tuning Parameters**, **Perform Forced CO2 Recalibration, 4.8.33, Set CO2 Sensor Automatic Self Calibration, 4.8.36**, **4.8.38)** • Included new commands and minor updates to figures and drawings (**Figure 4**, **Get Version, Get SHT Heater Measurements, Technical Drawing)**
December 2025	V0.92	All	• Removed SEN60 and added SEN62, SEN69C • Increased max supply voltage to 3.6 V in **Table 11** • Added **Perform CO2 Sensor Factory Reset**

Important Notices

Warning, Personal Injury

Do not use this product as safety or emergency stop devices or in any other application where failure of the product could result in personal injury (including death). Do not use this product for applications other than its intended and authorized use. Before installing, handling, using or servicing this product, please consult the data sheet and application notes. Failure to comply with these instructions could result in death or serious injury.

If the Buyer purchases or uses SENSIRION products for any unintended or unauthorized application, Buyer shall defend, indemnify and hold harmless SENSIRION and its officers, employees, subsidiaries, affiliates and distributors against all claims, costs, damages and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if SENSIRION is allegedly negligent with respect to the design or the manufacture of the product.

ESD Precautions

The inherent design of this component causes it to be sensitive to electrostatic discharge (ESD). To prevent ESD-induced damage and/or degradation, take customary and statutory ESD precautions when handling this product. See application note "ESD, Latchup and EMC" for more information.

Warranty

SENSIRION solely warrants to the original purchaser of this product for a period of 12 months (one year) from the date of delivery that this product is of the quality, material and workmanship defined in SENSIRION's published specifications of the product. Within such period, if proven to be defective, SENSIRION shall as sole and exclusive remedy, in SENSIRION's discretion, repair this product or send a replacement product, free of charge to the Buyer, provided that:

- notice in writing describing the defects shall be given to SENSIRION within fourteen (14) days after their appearance;
- such defects shall be found, to SENSIRION's reasonable satisfaction, to have arisen from SENSIRION's faulty material or workmanship;
- the defective product shall be returned to SENSIRION's factory at the Buyer's expense; and
- the warranty period for any repaired or replaced product shall be limited to the unexpired portion of the original period.

The Buyer shall at its own expense arrange for any dismantling and reassembly that is necessary to repair or replace the defective product. This warranty does not apply to any product which has not been installed or used within the specifications recommended by SENSIRION. EXCEPT FOR THE WARRANTIES EXPRESSLY SET FORTH HEREIN, SENSIRION MAKES NO WARRANTIES, EITHER EXPRESS OR IMPLIED, WITH RESPECT TO THE PRODUCT. ANY AND ALL WARRANTIES, INCLUDING WITHOUT LIMITATION, WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE, ARE EXPRESSLY EXCLUDED AND DECLINED.

SENSIRION is only liable for defects of this product arising under the conditions of operation provided for in the data sheet and proper use of the goods. SENSIRION explicitly disclaims all warranties, express or implied, if the goods are operated or stored not in accordance with the technical specifications.

SENSIRION does not assume any liability arising out of any application or use of any product or circuit and specifically disclaims any and all liability, including without limitation indirect, consequential, and incidental damages, and loss of profit. No obligation or liability shall arise or grow out of SENSIRION's rendering of technical advice, consulting, or implementation instructions or guidelines. All operating parameters, including without limitation recommended parameters, must be validated for each Buyer's applications by Buyer's technical experts. Recommended parameters can and do vary in different applications.

SENSIRION reserves the right, without further notice, (i) to change the product specifications and/or the information in this document and (ii) to improve reliability, functions and design of this product.

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